## ASR-2000 / ASR-3000 Series Programmable AC/DC Power Source

## Utilize ASR-2000/3000 AC/DC power source for LV124 \& LV148



LV 124 Electric and Electronic Components in Motor Vehicles up to 3.5 t with a 12 V electric system General Requirements Test Conditions and Tests

LV 148 Electric and Electronic Components for Vehicles with a 48V Electrical System Test Conditions and Tests

### 1.1.1 Tolerances

| Standard tolerances |  | LV 124 | LV 148 | Standard values |  | LV 124 | LV 148 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Parameter | Tolerance |  | Parameter |  | Tolerance |  |
| f | Frequencies | $\pm 1 \%$ | $\pm 1 \%$ | TRT | Room temperature | $23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}$ | $23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}$ |
| T | Temperature | $\pm 2^{\circ} \mathrm{C}$ | $\pm 2^{\circ} \mathrm{C}$ | Frel | Humidity | 25 \% to 75 \% rel. humidity | $25 \%$ (+5 to 0 \%) up to $75 \%$ (-5 to $0 \%$ ) rel. humidity |
| Frel | Humidity | $\pm 5 \%$ | $\pm 5 \%$ |  |  |  |  |
| t | Times | + 5 \%; $0 \%$ | + 5 \%; $0 \%$ | Ttest | Test temperature | TRT room temperature | TRT room temperature |
| U | Voltages | $\pm 2 \%$ | $\pm 0.5 \%$ | UB | Operating voltage (for test) | $U B=14 \mathrm{~V}$ | U48x |
| I | Current | $\pm 2 \%$ | $\pm 2 \%$ | Ri | Source impedance | $\mathrm{Ri} \leqq 100 \mathrm{~m} \Omega$ (E6) | $10 \mathrm{~m} \Omega \leqq \mathrm{Ri} \leqq 100 \mathrm{~m} \Omega$ |
|  |  |  |  |  |  | $\mathrm{Ri}<30 \mathrm{~m} \Omega / 100 \mathrm{~m} \Omega$ (E15) |  |

1.1.2 Operating voltage range LV 124 / LV 148

| Code | Ubmin | Ubmax | Function / description LV 124 |
| :--- | :--- | :--- | :--- |
| a | 6 V | 16 V | For functions that must retain their |
|  |  |  | performance during starting of the engine |
| b | 8 V | 16 V | For functions that do not have to retain their |
|  |  |  | performance during starting of the engine |
|  |  |  | This encoding must only be used if the |
|  |  |  | component cannot be classified in the |
|  |  |  | encoding a, c or d. |
| c | 9 V | 16 V | For functions that must retain their |
|  |  |  | performance when the engine is not |
|  |  |  | running |
| d | 9.8 V | 16 V | For functions that must retain their |
|  |  |  | performance when the engine is running |


| Shortcut | Terms LV 148 | Values |
| :--- | :--- | :--- |
| U48r,dyn | Lower voltage limit of the dynamic overvoltage range | 60 V |
| U48r | Lower voltage limit of the 2 V tolerance to the dynamic <br> overvoltage range | 58 V |
| U48max, high,limited | Max. voltage of the upper operating range with functional <br> restriction | 54 V |
| U48max, unlimited | Max. voltage of the operating range without functional <br> restriction | 52 V |
| U48n | BN48- nominal voltage | 48 V |
| U48min,unlimited | Min. voltage of the operating range without functional <br> restriction | 24 V |
| U48min,low,limited | Min. voltage of the lower operating range with functional <br> restriction | 20 V |
| U48stoprotect | Accumulator protected voltage |  |
| U48pp | Peak - peak- voltage |  |
| U48rms | Effektive value of a voltage |  |
| U48max | Maximum voltage that may occur during a test |  |
| U48min | Minimum voltage that may occur during a test |  |
| U48test | BN48- test voltage | 28 V |
| U12test | BN12- test voltage |  |
| U24test | BN24- test voltage |  |

## ASR-2000/2000R Series Programmable AC/DC Power Source

## Need an AC+DC waveform power source?



Features

- Output Capacity: 500VA/500W ASR-2050(R), 1000VA/1000W ASR-2100(R)
- Output Rating: AC; $0-350 \mathrm{Vrms}(@ 200 \mathrm{~V}$ range), DC, AC+DC; $0- \pm 500 \mathrm{~V}(@ 200 \mathrm{~V}$ range)
- Output mode: AC+DC-INT, AC-INT, DC-INT, AC+DC-EXT, AC-EXT, AC+DC-ADD, AC-ADD, AC+DC-SYNC, AC-SYNC
- Output Frequency: AC+DC mode; DC, 1 Hz to 999.9 Hz, AC mode; 40 Hz to 999.9 Hz
- DC Output ( $100 \%$ of Rated Power): $0- \pm 500 \mathrm{~V}$
- Measurement Items: Vrms, Vavg, Vpeak, Irms, IpkH, Iavg, Ipeak, P, S, Q, PF, CF, Voltage and Current Harmonic Analysis: THDv, THDi
- Remote Sensing
- Protection: OVP, OCP, OPP, OTP, AC Fail Detection and Fan Fail Alarm.
- Arbitrary Waveform Function: 16-bit, 4096 words, 16 ARB waveform memories
- Output On/Off Phase Angle control: $0.0^{\circ}$ to $359.9^{\circ}$, variable (setting resolution $0.1^{\circ}$ )
- Sequence Function: up to 999 steps, , up to 10 memories, Mode; DC-INT, AC-INT, and AC+DC-INT
- Simulation Function: 6 steps(Init, Normal1, Trans1, Abnormal, Trans2, Normal2, Init), up to 10 memories, Mode; AC+DC-INT
- Interface: USB Device and , LAN as standard, RS-232+GPIB as optional
- External Control I/O: Input; Sequence control (Start, Stop, Hold, branch 1/2,

Output; Power source on/off, Output on/off, Software busy, Sequence sync output 0/1

- External Signal Input: SYNC mode; Synchronizing the output frequency with this external input signal

EXT and ADD mode: Outputting the amplified external input signal with input signal.

- Built-in Output Relay Control

| Model |  |  | ASR-2050 / ASR-2050R |  | ASR-2100 / ASR-2100R |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Output Rating for AC Mode |  |  |  |  |  |  |
| Range |  |  | 100 V | 200 V | 100 V | 200 V |
| Voltage |  | Setting Range | 0.0 V to 175.0 V , | 0.0 V to 350.0 V | 0.0 V to 175.0 V | 0.0 V to 350.0 V |
|  |  | Setting Resolution | 0.1 V |  |  |  |
|  |  | Accuracy*2 | $\pm$ (0.5 \% of set $+0.6 \mathrm{~V} / 1.2 \mathrm{~V}$ ) |  |  |  |
| Output phase |  |  | Single phase, Two-wire |  |  |  |
| Maximum current*3 |  |  | 5 A | 2.5 A | 10 A | 5 A |
| Maximum peak current*4 |  |  | 20 A | 10 A | 40 A | 20 A |
| Power capacity |  |  | 500 VA |  | 1000 VA |  |
| Frequency | Setting range | AC Mode: | 40.00 Hz to 999.9 Hz |  |  |  |
|  |  | AC+DC Mode: | 1.00 Hz to 999.9 Hz |  |  |  |
|  | Setting resolution |  | 0.01 Hz (1.00 to 99.99 Hz ), 0.1 Hz ( 100.0 to 999.9 Hz ) |  |  |  |
| Output on phase |  |  | $0.0^{\circ}$ to $359.9^{\circ}$ variable (setting resolution $0.1^{\circ}$ ) |  |  |  |
| DC offset*6 |  |  | Within $\pm 20 \mathrm{mV}$ (TYP) |  |  |  |
| Output Rating for DC Mode |  |  |  |  |  |  |
| Range |  |  | 100 V | 200 V | 100 V | 200 V |
| Voltage |  | Setting Range | -250 V to +250 V | -500 V to +500 V | -250 V to +250 V | -500 V to +500 V |
|  |  | Setting Resolution | 0.1 V |  |  |  |
|  |  | Accuracy*2 | $\pm(\mid 0.5 \%$ of set $\mid+0.6 \mathrm{~V} / 1.2 \mathrm{~V})$ |  |  |  |
| Maximum current*3 |  |  | 5 A | 2.5 A | 10 A | 5 A |
| Maximum peak current*4 |  |  | 20 A | 10 A | 40 A | 20 A |
| Power capacity |  |  | $500 \text { W }$ |  | $1000 \text { W }$ |  |

LV 124 \& LV 148
Automotive Testing

## ASR-3000 Series Programmable AC/DC Power Source

## 2000VA ASR-3200 3000VA ASR-3300 4000VA ASR-3400



Features

- Output Capacity: 2000VA/2000W ASR-3200, 3000VA/3000W ASR-3300
- Output Rating: AC $0-400 \mathrm{Vrms}, \mathrm{DC} 0- \pm 570 \mathrm{~V} @ 200 \mathrm{~V}$ range
- Output mode: AC+DC-INT, AC-INT, DC-INT, AC+DC-EXT, AC-EXT, AC+DC-ADD, AC-ADD, AC+DC-SYNC, AC-SYNC
- Output Frequency: AC+DC mode; DC, 1 Hz to $999.9 \mathrm{~Hz}, \mathrm{AC}$ mode; 40 Hz to 999.9 Hz
- DC Output: ( $100 \%$ of Rated Power): $0- \pm 570 \mathrm{~V}$
- Measurement Items: Vrms, Vavg, Vpeak, Irms, IpkH, lavg, Ipeak, P, S, Q, PF, CF, Voltage and Current Harmonic Analysis(THDv, THDi)
- Remote Sensing
- Protection: OCP, OPP, OTP, AC Fail Detection and Fan Fail Alarm.
- Arbitrary Waveform Function: 16-bit, 4096 words, 16 ARB waveform memories
- Output On/Off Phase Angle control: $0.0^{\circ}$ to $359.9^{\circ}$, variable (setting resolution $0.1^{\circ}$ )
- Sequence Function: up to 999 steps, , up to 10 memories, Mode; DC-INT, AC-INT, and AC+DC-INT
- Simulation Function: 6 steps(Init, Normal1, Trans1, Abnormal, Trans2, Normal2, Init), up to 10 memories, Mode; AC+DC-INT
- Interface(std): USB, LAN, RS-232, GPIB
- External Control I/O: Input; Sequence control (Start, Stop, Hold, branch 1/2, Output; Power source on/off, Output on/off, Software busy, Sequence sync output 0/1
- External Signal Input: SYNC mode; Synchronizing the output frequency with this external input signal

EXT and ADD mode: Outputting the amplified external input signal with input signal.

- Built-in Output Relay Control
- Built-in Web Server

| Model |  |  | ASR-3200 |  | ASR-3300 |  | ASR-3400 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Output Rating for AC Mode |  |  |  |  |  |  |  |  |
| Range |  |  | 100 V | 200 V | 100 V | 200 V | 100 V | 200 V |
| Voltage |  | Setting Range | 0.0 V to 200.0 V | 0.0 V to 400.0 V | 0.0 V to 200.0 V | 0.0 V to 400.0 V | 0.0 V to 200.0 V | 0.0 V to 400.0 V |
|  |  | Setting Resolution | 0.1 V |  |  |  |  |  |
|  |  | Accuracy*2 | $\pm$ (0.5 \% of set $+0.6 \mathrm{~V} / 1.2 \mathrm{~V}$ ) |  |  |  |  |  |
| Output phase |  |  | Single phase, Two-wire |  |  |  |  |  |
| Maximum current*3 |  |  | 20A | 10 A | 30 A | 15 A | 40 A | 20 A |
| Maximum peak current*4 |  |  | 120 A | 60 A | 180 A | 90 A | 240 A | 120 A |
| Power capacity |  |  | 2000 VA |  | 3000 VA |  | 4000 VA |  |
| Frequency | Setting range | AC Mode: | 40.00 Hz to 999.9 Hz |  |  |  |  |  |
|  |  | AC+DC Mode: | 1.00 Hz to 999.9 Hz |  |  |  |  |  |
|  | Setting resolution |  | 0.01 Hz (1.00 to 99.99 Hz ), 0.1 Hz ( 100.0 to 999.9 Hz ) |  |  |  |  |  |
| Output on phase |  |  | $0.0^{\circ}$ to $359.9^{\circ}$ variable (setting resolution $0.1^{\circ}$ ) |  |  |  |  |  |
| DC offset*6 |  |  | Within $\pm 20 \mathrm{mV}$ (TYP) |  |  |  |  |  |
| Output Rating for DC Mode |  |  |  |  |  |  |  |  |
| Range |  |  | 100 V | 200 V | 100 V | 200 V | 100 V | 200 V |
| Voltage |  | Setting Range | -285 V to +285 V | -570 V to +570 V | -285 V to +285 V | -570 V to +570 V | -285 V to +285 V | -570 V to +570 V |
|  |  | Setting Resolution | 0.1 V |  |  |  |  |  |
|  |  | Accuracy*2 | $\pm(\mid 0.5 \%$ of set\| $+0.6 \mathrm{~V} / 1.2 \mathrm{~V})$ |  |  |  |  |  |
| Maximum current*3 |  |  | 20 A | 10 A | 30 A | 15 A | 40 A | 20 A |
| Maximum peak current*4 |  |  | 120 A | 60 A | 180 A | 90 A | 240 A | 120 A |
| Power capacity |  |  | 2000 W |  | 3000 W |  | 4000 W |  |

The ASR series have a powerful sequence function that can create complex output waveforms.
The sequence feature works in DC-INT, AC-INT, and AC+DC-INT modes and includes DC, sine, square, triangle, and 16 arbitrary waveforms.
The sequence function consists of a total of 1000 steps ( 0 to 999 step).
Available parameters and waveforms depend on the selected output mode.
Each step can set the waveform, Voltage, and duration Time and select the behavior (constant/hold/sweep) for each step.
It also has a branch function to a specified step during sequence operation. All sequence data can save 10 internal sequence memories (SEQ0 to SEQ9) or external USB sticks.
Since the sequence function can control Start, Stop, Hold, and Branch from the External Control I/O, it can be used in combination with an external device.

## PC Software of ASR

Sequence screen


## [Output parameters]

- Time: 0.0001 ~ 999.9999s,resolution 0.0001s
- AC voltage ${ }^{* 1}$ : 0.0-350.0V (Range 200V) , 0.0-175.0V (Range 100V)
- DC voltage ${ }^{{ }^{*} 1}: 0.0- \pm 500.0 \mathrm{~V}$ (Range 200V), $0.0- \pm 250.0 \mathrm{~V}$ (Range 100V)
- Frequency: 1.00-999.9Hz (AC+DC-INT) , 40.00-999.9(AC-INT)
- Waveform: SIN / SQU / TRI / ARB1 to ARB16 (AC-DC-INT/AC-INT)
- On / OFF Phase: Free, Fixed ( 0.0 ~ $359.9^{\circ}$ )
- Sync Code ${ }^{* 2}$ : Sequence sync output $0(\mathrm{~L}) / 1(\mathrm{H})$ via External I/O connector


## [Step operation types]

ACV/DCV Behaivior

- CONST: the step immediately to setting values.
- KEEP : Keep the value of the previous step.
- SWEEP: Linearly increases or decreases the values from the end of the previous step to the end of the current step.
*: Maximum output voltage: ASR-2000; 500Vpp = DC+ACpp, ASR-3000; 570Vpp=DC+ACpp

Number of sequences:
Number of steps:
Step time:
Operations within step:
Parameter:
Jump times:
ON/OFF Phs

Retained for each operation mode (DC-INT, AC-INT and AC+DC-INT) and output voltage range ( $100 \mathrm{~V} / 200 \mathrm{~V}$ ). 1 to 999 (per sequence) , Step 0 is assigned as a "Standby" step
0.1 ms to 999.9999 s (resolution 0.1 ms or 0.0001 s )

CT(Constant), KP(Keep), or SP(Linear Sweep)
DC voltage, AC voltage, frequency, waveform, phase (start, end), step synchronized output (2 bits)
1 to 999 or infinite
Sets the start and stop phase of the AC waveform for each step. (AC+DC-INT and AC-INT modes)

## E-01 Long-term over voltages

The component's resistance to long-term overvoltage is tested. A generator control
fault during driving operation is simulated.


## LV 124

Mode: DC-INT


| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.0100 | 0.0100 | 0.0100 | 600.00 | 600.00 | 0.0100 | 0.6000 |
| DCV [V] | 13.5 | 13.5 | 17.0 | 17.0 | 17.0 | 13.5 | 13.5 |
| DCV Behavior | CONST | CONST | SWEEP | KEEP | KEEP | SWEEP | END |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE |
| Jump-To | 0 | 0 | 0 | 0 | 3 | 0 | 0 |
| Jump |  | OFF | OFF | OFF | ON | OFF | ON |
| Jump Cnt | 0 | 0 | 0 | 0 | 2 | 0 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL | LL |

## LV 148

Mode: DC-INT
Repeat

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.0100 | 0.0100 | 0.1000 | 600.00 | 600.00 | 0.1000 | 1.0000 |
| DCV [V] | 48.0 | 48.0 | 60.0 | 60.0 | 60.0 | 48.0 | 48.0 |
| DCV Behavior | CONST | CONST | SWEEP | KEEP | KEEP | SWEEP | END |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE |
| Jump-To | 0 | 0 | 0 | 0 | 3 | 0 | 0 |
| Jump |  | OFF | OFF | OFF | ON | OFF | ON |
| Jump Cnt | 0 | 0 | 0 | 0 | 2 | 0 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL | LL |

Note: This waveform changed 600 min to 0.6 s .



Note: This waveform changed 600 s to 6.0 s .

## E02 Transiente overvoltages

Transient overvoltages may occur in the electric system due to the switching off of loads and due to short accelerator tip-ins. These overvoltages are simulated by means of this.


LV 124:3 Test cases on different temperatures; Functional status: A

## LV 124

Mode: DC-INT

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.0100 | 0.0010 | 0.0400 | 0.0010 | 0.600 | 0.1000 | 0.6000 | 0.6000 |
| DCV $[\mathrm{V}]$ | 16.0 | 18.0 | 18.0 | 17.0 | 17.0 | 16.0 | 16.0 | 16.0 |
| DCV Behavior | CONST | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP | END |

Termination $\quad$ CONTINUE CONTINUE CONTINUE CONTINUE CONTINUE CONTINUE CONTINUE CONTINUE

| Jump-To | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Jump |  | OFF | OFF | OFF | OFF | OFF | ON | OFF |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL | LL | LL |



## LV 148

| LV 148 | 70 V <br> 58 V <br> 48 V |  |  |  |
| :---: | :---: | :---: | :---: | :---: |

LV 148: 2 tests, short test 3x, long duration test 1000x, Ri: $10 \mathrm{~m} \Omega \leq \mathrm{Ri} \leq 100 \mathrm{~m} \Omega$ Functional status: A
Mode: DC-INT

| Repeat |  |  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| Time[ms] | 0.1000 | 0.0010 | 0.0400 | 0.0010 | 0.600 | 0.1000 | 2.5000 | 2.0000 |
| DCV [V] | 48.0 | 70.0 | 70.0 | 58.0 | 58.0 | 48.0 | 48.0 | 48.0 |
| DCV Behavior | CONST | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP | END |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE |
| Jump-To | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| Jump |  | OFF | OFF | OFF | OFF | OFF | ON | OFF |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 0 | 3 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL | LL | LL |



## E-03, E48-03

## Transiente Undervoltages

Transient undervoltages in the electric system may occur due to switching on of loads.
These undervoltages are simulated by means of this test.


LV 124
Mode: DC-INT Repeat

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.1000 | 0.0180 | 0.5000 | 0.0180 | 1.000 | 1.0000 |
| DCV [V] | 10.8 | 9.0 | 9.0 | 10.8 | 10.8 | 10.8 |
| DCV Behavior | CONST | SWEEP | KEEP | SWEEP | KEEP | KEEP |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | END |
| Jump-To | 0 | 0 | 0 | 0 | 1 | 0 |
| Jump |  | OFF | OFF | OFF | ON | OFF |
| Jump Cnt | 0 | 0 | 0 | 0 | 2 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL |




LV 148
Mode: DC-INT
Mode: DC-INT

| Step No. | 0 | 1 | $t_{0}$ | $\mathrm{tf}_{6}$ | $\mathrm{t}_{1}$ | $\mathrm{t}_{\mathrm{r}}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{2}$ |  |  |  |  |  |  |
| Time[ms] | 0.0100 | 60.000 | 0.0020 | 0.5000 | 0.0020 | 0.5000 |
| DCV [V] | 0.0 | 36.0 | 24.0 | 24.0 | 36.0 | 48.0 |
| DCV Behavior | CONST | CONST | SWEEP | KEEP | SWEEP | SWEEP |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | END |
| Jump-To | 0 | 0 | 0 | 0 | 0 | 0 |
| Jump |  | OFF | OFF | OFF | OFF | OFF |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL |



## E-04, E

## Jumpstart, resp. Recuperation

Jump starting of the vehicle is simulated. The maximum test voltage results from commercial vehicle systems and their elevated electric system voltages. LV 148: Longer recuperation is simulated


Number of cycles:
1
LV 124
Mode: DC-INT

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.0100 | 20.000 | 0.0100 | 60.00 | 0.0100 | 0.0100 | 0.6000 |
| DCV [V] | 0.0 | 10.8 | 26.0 | 26.0 | 10.8 | 13.5 | 13.5 |
| DCV Behavior | CONST | CONST | SWEEP | KEEP | SWEEP | KEEP | END |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE |
| Jump-To | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Jump |  | OFF | OFF | OFF | OFF | OFF | ON |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL | LL |

Number of cycles:
1

## LV 148

Mode: DC-INT
6

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 0.0100 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.0100 | 60.000 | 0.1000 | 60.00 | 0.1000 | 60.0000 | 0.0 |
| DCV [V] | 0.0 | 52.0 | 54.0 | 54.0 | 52.0 | 52.0 | END |
| DCV Behavior | CONST | CONST | SWEEP | KEEP | SWEEP | KEEP | CONTINUE |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | 0 |
| Jump-To | 0 | 0 | 0 | 0 | 0 | 0 | ON |
| Jump |  | OFF | OFF | OFF | OFF | OFF | 0 |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | OFF |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | 0 |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | OFF |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | LL |
| Code | LL | LL | LL | LL | LL | LL |  |



## E-07 Slow decrease and increase of the supply voltage

The slow decrease and increase of the supply voltage is simulated as it occurs during the slow discharging and charging procedure of the vehicle battery.


The maximum Step time for Sequence mode is 999.9999 seconds. If you want to set a time that exceeds the maximum step time, you can set it by combining steps.


Number of cycles: 1
t1/t2: Holding time at V1/V2 until event memory has been completely read out

## LV 124

| Mode: DC |  | $V_{\text {Bmin }}=9.8 \mathrm{~V}$ |  | $\xrightarrow{19.6 \mathrm{~min}}$ |  | $\xrightarrow{19.6 \mathrm{~min}}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| Time[ms] | 0.0100 | 744.0000 | 10.0000 | 600.0000 | 576.0000 | 576.0000 | 600.0000 | 10.0000 | 744.0000 |
| DCV [V] | 16.0 | 9.8 | 9.8 | 4.8 | 0 | 4.8 | 9.8 | 9.8 | 16.0 |
| DCV Behavior | CONST | SWEEP | KEEP | SWEEP | SWEEP | SWEEP | SWEEP | KEEP | SWEEP |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | END |
| Jump-To | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Jump |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL | LL | LL | LL |

In the figure below, the steps time changed so that the overall image is easy to understand.


## E48-06a Slow decrease and increase of the supply voltage

The slow decrease and increase of the supply voltage is simulated as it occurs during the slow discharging and
charging procedure of the vehicle battery.


The maximum Step time for Sequence mode is 999.9999 seconds. If you want to set a time that exceeds the maximum step time, you can set it by combining steps.


Number of cycles: 1
t1/t2: Holding time at V1/V2 until event memory has been completely read out

Number of cycles:
1
Functional status: depends on voltage range
LV 148
Mode: DC-INT

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.0100 | 540.0000 | 10.000 | 540.0000 | 540.0000 | 540.0000 | 540.0000 | 10.0000 | 540.0000 |
| DCV [V] | 52.0 | 36.0 | 36.0 | 18.0 | 0 | 18.0 | 36.0 | 36.0 | 52.0 |
| DCV Behavior | CONST | SWEEP | KEEP | SWEEP | SWEEP | SWEEP | SWEEP | KEEP | SWEEP |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE |
| Jump-To | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Jump |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 1 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Branch 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Branch 2 |  | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |
| Code | LL | LL | LL | LL | LL | LL | LL | LL | LL |

In the figure below, the steps time changed so that the overall image is easy to understand.


## E-08, E48-07 Slow decrease, fast increase in the supply voltage

LV 124 This test simulates the slow decrease of the battery voltage to $\mathbf{0 V}$ and the sudden reapplication of the battery voltage, e.g., by applying a jump start source.
LV 148 This test simulates the slow decrease of the vehicle system voltage to the energy storage protection voltage followed by shutdown to OV and the sudden reconnect the system voltage by a charged or new energy storage battery.


Number of cycles: 1 per operating mode II.a / II.c
t1: Holding time at V1 until event memory has been completely read out
t2: At least 1 min ; however, as long as internal capacity is completely discharged


In the figure below, the steps time changed so that the overall image is easy to understand.


## E-09, E48-08 Reset behavior

The reset behavior of a component in its environment is simulated and tested. Test boundary conditions (e.g., assembly, terminal, system) must be described in detail. During operation, an arbitrary sequence of repeated switching-on/off procedures occurs; this must not lead to an undefined behavior of the component. The reset behavior is represented by a voltage variance and a time variance. Two different test sequences are required to simulate different switch-off times. A component must always undergo both sequences.


LV 124

| Jump-To | 0 |
| :--- | :---: |
| Jump | OFF |
| Jump Cnt | 0 |
| Branch 1 | 0 |
| Branch 1 | OFF |
| Branch 2 | 0 |
| Branch 2 | OFF |
| Code | LL |

Mode: DC-INT $9.8 \mathrm{~V} \longleftarrow \Delta \mathrm{~V}_{1}=0.5 \mathrm{~V}$

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 27 | 28 | 29 | 30 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 10.0000 | 0.0100 | 5.0000 | 0.0100 | 10.0000 | 0.0100 | 5.0000 | 0.0100 | 10.0000 | 0.0100 | 5.0000 |
| DCV [V] | 9.8 | 9.3 | 9.3 | 9.8 | 9.8 | 8.8 | 8.8 | 9.8 | 9.8 | 6.0 | 6.0 |
| DCV Behavior | CONST | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | $5.8 \mathrm{~V} \longleftrightarrow 0.0 \mathrm{~V}$


| Step No. | 31 | 32 | 33 | 34 | 35 | 36 | 37 | 149 | 150 | 151 | 152 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 0.0100 | 10.0000 | 0.0100 | 5.0000 | 0.0100 | 10.0000 | 0.0100 | 0.0100 | 10.0000 | 0.0100 | 10.0000 |
| DCV [V] | 9.8 | 9.8 | 5.8 | 5.8 | 9.8 | 9.8 | 5.6 | 0.0 | 0.0 | 9.8 | 9.8 |
| DCV Behavior | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP | SWEEP | SWEEP | KEEP | SWEEP | KEEP |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | END |

In the figure below, the steps time changed so that the overall image is easy to understand.


## E-09, E48-08 Reset behavior

The reset behavior of a component in its environment is simulated and tested. Test boundary conditions (e.g., assembly, terminal, system) must be described in detail. During operation, an arbitrary sequence of repeated switching-on/off procedures occurs; this must not lead to an undefined behavior of the component. The reset behavior is represented by a voltage variance and a time variance. Two different test sequences are required to simulate different switch-off times. A component must always undergo both sequences.


LV 148

| ump-To | 0 |
| :--- | :---: |
| Jump | OFF |
| Jump Cnt | 0 |
| Branch 1 | 0 |
| Branch 1 | OFF |
| Branch 2 | 0 |
| Branch 2 | OFF |
| Code | LL |

$$
\text { Mode: DC-INT } 52.0 \mathrm{~V} \longleftrightarrow \Delta \mathrm{~V}_{1}=2.0 \mathrm{~V} \longrightarrow 24.0 \mathrm{~V}
$$



| $\Delta \mathrm{V}_{1}=0.5 \mathrm{~V}$ |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Step No. | 55 | 56 | 57 | 56 | 57 | 58 | 59 | 245 | 246 | 247 | 248 |
| Time[ms] | 0.1000 | 10.0000 | 0.1000 | 5.0000 | 0.1000 | 10.0000 | 0.1000 | 0.1000 | 10.0000 | 0.1000 | 10.0000 |
| DCV [V] | 52.0 | 52.0 | 23.5 | 23.5 | 52.0 | 52.0 | 23.0 | 0.0 | 0.0 | 52.0 | 52.0 |
| DCV Behavior | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP | SWEEP | SWEEP | KEEP | SWEEP | KEEP |
| Termination | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | CONTINUE | END |



## E-11 Start impulse

When starting the engine, the battery voltage falls for a short period to a low value, and then again to rise slightly.
The start process can happen under different vehicle start situations: To cover both cases at cold start and warm start two different test cases are required. A component has always to go through both test procedures.

## Test case 1 : Cold start Normal

At test case 1 cold start (start the engine), there are test impulses for: "normal" for normal cold start and "severe " with a lower battery voltage consider when starting the engine.

At test case 2 warm start (automatic restart after a stop), there are two cycles: Short: 5 seconds break $10 \times$ Long: 20 seconds break 100 cycles
Number of samples: at least 6

## Example: Normal



Note: The time axis scale is not the actual ratio.
Mode: AC/DC-INT

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 1.0000 | 1.0000 | 0.0010 | 0.0190 | 0.0500 | 10.0000 | 0.1000 | 1.0000 |
| ACV [Vrms] | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.7 | 0.0 | 0.0 |
| ACV Behavior | CONST | CONST | CONST | CONST | CONST | CONST | CONST | CONST |
| DCV [V] | 11.0 | 11.0 | 4.5 | 4.5 | 6.5 | 7.5 | 11.0 | 11.0 |
| DCV Behavior | CONST | CONST | SWEEP | CONST | SWEEP | CONST | SWEEP | CONST |
| Frequency [Hz] | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 2.0 | 60.0 | 60.0 |
| Frequency Behavior | CONT | CONT | CONT | CONT | CONT | CONT | CONT | CONT |
| Waveform | SIN | SIN | SIN | SIN | SIN | SIN | SIN | SIN |
| Termination | Continue | Continue | Continue | Continue | Continue | Continue | Continue | Continue |
| On Phase [Degree] | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 270.0 | 0.0 | 0.0 |
| On Pase | OFF | OFF | OFF | OFF | OFF | ON | OFF | OFF |



## E-11 Start impulse

## Test case1: Cold start Severe

At test case 1 cold start (start the engine), there are test impulses for: "normal" for normal cold start and "severe " with a lower battery voltage consider when starting the engine.
At test case 2 warm start (automatic restart after a stop), there are two cycles: Short: $\mathbf{5}$ seconds break $10 \times$ Long: 20 seconds break 100 cycles
Number of samples: at least 6

## Example: Severe



Note: The time axis scale is not the actual ratio.
Mode: AC/DC-INT

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 1.0000 | 1.0000 | 0.0010 | 0.0190 | 0.0500 | 10.0000 | 0.1000 | 1.0000 |
| ACV [Vrms] | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.7 | 0.0 | 0.0 |
| ACV Behavior | CONST | CONST | CONST | CONST | CONST | CONST | CONST | CONST |
| DCV [V] | 11.0 | 11.0 | 4.5 | 4.5 | 6.5 | 7.5 | 11.0 | 11.0 |
| DCV Behavior | CONST | CONST | SWEEP | CONST | SWEEP | CONST | SWEEP | CONST |
| Frequency [Hz] | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 2.0 | 60.0 | 60.0 |
| Frequency Behavior | CONT | CONT | CONT | CONT | CONT | CONT | CONT | CONT |
| Waveform | SIN | SIN | SIN | SIN | SIN | SIN | SIN | SIN |
| Termination | Continue | Continue | Continue | Continue | Continue | Continue | Continue | Continue |
| On Phase [Degree] | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 270.0 | 0.0 | 0.0 |
| On Pase | OFF | OFF | OFF | OFF | OFF | ON | OFF | OFF |



## E-11 Start impulse

## Test Case 2: Start pulses Hot start

Example: Start pulses Hoț start


Note: The time axis scale is not the actual ratio.

|  | $\mathrm{t}_{\text {test }}$ |  |  |  |  |  |  |  |  | C |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Mode: DC-INT | a | b |  |  |  |  |  |  |  |  |
| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| Time[ms] | 0.1000 | 0.0100 | 0.0010 | 0.0150 | 0.0700 | 0.2400 | 0.0700 | 0.6000 | 0.0010 | 0.1000 |
| ACV [Vrms] | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 |
| ACV Behavior | CONST | CONST | CONST | CONST | CONST | CONST | CONST | CONST | CONST | CONST |
| DCV [V] | 11.0 | 11.0 | 7.0 | 7.0 | 8.0 | 8.0 | 9.0 | 9.0 | 11.0 | 11.0 |
| DCV Behavior | CONST | CONST | SWEEP | CONST | SWEEP | KEEP | SWEEP | KEEP | SWEEP | KEEP |
| Frequency [Hz] | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 |
| Frequency Behavior | CONT | CONT | CONT | CONT | CONT | CONT | CONT | CONT | CONT | CONT |
| Waveform | SIN | SIN | SIN | SIN | SIN | SIN | SIN | SIN | SIN | SIN |
| Termination | Continue | Continue | Continue | Continue | Continue | Continue | Continue | Continue | Continue | Continue |
| On Phase [Degree] | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 |
| On Pase | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF | OFF |



## E-12 Voltage curve with electric system control

The behavior of the electric system with voltage controls, e.g., with the use of intelligent generator controls or DC-DC converter controls, is simulated.


Repeat

| Step No. | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time[ms] | 1.0000 | 0.3000 | 0.3000 | 2.0000 | 0.3000 | 2.0000 | 0.1000 |
| ACV [Vrms] | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 |
| ACV Behavior | CONST | CONST | CONST | CONST | CONST | CONST | CONST |
| DCV [V] | 11.8 | 11.8 | 15.0 | 15.0 | 11.8 | 11.8 | 11.0 |
| DCV Behavior | CONST | KEEP | SWEEP | KEEP | SWEEP | KEEP | SWEEP |
| Frequency [Hz] | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 | 60.0 |
| Frequency Behavior | CONT | CONT | CONT | CONT | CONT | CONT | CONT |
| Waveform | SIN | SIN | SIN | SIN | SIN | SIN | SIN |
| Termination | Continue | Continue | Continue | Continue | Continue | Continue | END |
| Jump-To | 0 | 0 | 0 | 0 | 0 | 2 | 0 |
| Jump | OFF | OFF | OFF | OFF | OFF | ON | OFF |
| Jump Cnt | 0 | 0 | 0 | 0 | 0 | 10 | 0 |

Operating mode of DUT Operating mode II.c

Vmin
Vmax
t1
tr
tf
Number of cycles
Number of samples
( $11,8 \mathrm{~V}-\Delta \mathrm{V}$ ) ( 0 \%, $-4 \%)$
( $15 \mathrm{~V}-\Delta \mathrm{V}$ ) (+4 \%, 0 \%)
2 s
$\geq 300 \mathrm{~ms}$
$\geq 300 \mathrm{~ms}$
10
at least 6

Test case 1: $\Delta \mathrm{V}=0.0 \mathrm{~V}$


Test case 2: $\Delta \mathrm{V}=0.7 \mathrm{~V}$


Test case 3: $\Delta \mathrm{V}=2.0 \mathrm{~V}$


