WT3000 SPEC

WT3000 Specifications

Inputs	
ltem	Specification
Input terminal type	Voltage
	Plug-in terminal (safety terminal)
	Current
	Direct input: Large binding post
and the second	External sensor input: Insulated BNC connector
nput type	Voltage
	Floating input, resistive potential method
	Current
Measurement range	Floating input, shunt input method Voltage
weasurement range	15 V, 30 V, 60 V, 100 V, 150 V, 300 V, 600 V, 1000 V (for crest factor 3)
	7.5 V, 15 V, 30 V, 50 V, 75 V, 150 V, 300 V, 500 V (for crest factor 6)
	Current
	Direct input
	500 mA, 1 A, 2 A, 5 A, 10 A, 20 A, 30 A (for crest factor 3)
	250 mA, 500 mA, 1 A, 2.5 A, 5 A, 10 A, 15 A (for crest factor 6)
	 External sensor input
	50 mV, 100 mV, 200 mV, 500 mV, 1 V, 2 V, 5 V, 10 V (for crest factor 3)
	25 mV, 50 mV, 100 mV, 250 mV, 500 mV, 1 V, 2.5 V, 5 V (for crest
	factor 6)
Instrument loss (input re	
	Voltage
	Approximately 10 MΩ // 5 pF
	Current
	• Direct input: Approximately 5.5 m Ω + approximately 0.03 μ H
Instantanoous maximum	• External sensor input: Approximately 1 MΩ n allowed input (1 second or less)
	Voltage
	Peak voltage of 2.5 kV or RMS of 1.5 kV, whichever is lower
	Current
	Direct input: Peak current of 150 A or RMS of 50 A, whichever is
	lower
	Current sensor input: Peak not to exceed 10 times the range
Continuous maximum a	
	Voltage
	Peak voltage of 1.6 kV or RMS of 1.1 kV, whichever is lower
	Current
	 Direct input: Peak current of 90 A or RMS of 33 A, whichever is
	lower
	Current sensor input: Peak not to exceed 5 times the range
Continuous maximum co	ommon mode voltage (50/60 Hz)
	1000 Vrms
Influence from common	
	Apply 1000 Vrms with the voltage input terminals shorted and the current input terminals open.
	• 50/60 Hz: ±0.01% of range or less
	Reference value up to 200 kHz
	Voltage:
	±3/range * f% of range or less. However, 3% or less.
	Current direct input and current sensor input:
	± (max. range/range)* 0.001 * f% of range or less.
	However, 0.01% or less. The units of f are kHz. The maximum rated
	range within equations is 30 A or 10 V.
Line filter	Select OFF, 500 Hz, 5.5 kHz, or 50 kHz.
Frequency filter	Select OFF, or ON
A/D converter	Simultaneous voltage and current conversion and 16-bit resolution.
	Conversion speed (sampling rate): Approximately 5 µsec. See
	harmonic measurement items for harmonic display. Approximately
	10 µsec for flicker display.
Range switching	Can be set for each input element.
Trigger range functions	Increasing range value
	 When the measured values of U and I exceed 110% of the range
	rating
	• When the peak value exceeds approximately 330% of the range
	rating (or approximately 660% for crest factor 6)
	 Decreasing range value When the measured values of U and I fall to 30% or less of the
	 when the measured values of 0 and 1 fail to 30% of less of the range rating, and Upk and Ipk are 300% or less of the lower
	ו וווי וטער מוע איז
	range value (or 600% for crest factor 6)
	range value (or 600% for crest factor 6)
	range value (or 600% for crest factor 6)

Display 8.4-inch color TFT LCD monitor Total number of pixels* 640 (horiz.) x 480 (vert.) dots Waveform display resolution 501 (horiz.) x 432 (vert.) dots Same as the data update rate. However, the rate is 250 msec when the data update rate is 50 or 100 msec Display update rate

* Up to 0.02% of the pixels on the LCD may be defective

Calculation Functions ingle-phase, 3 phase, 3 wir 3 phase, 4 wire 3 phase, 3 wire (3 voltage 3 current) (U1+U2)/2 UΣ (U1+U2+U3)/3 [V] 15 [A] (I1+I2)/2 (11+12+13)/3 P1+P2+P3 ΡΣ [W] P1+P2 [VA] S1+S2 SΣ TYPE1 $\frac{\sqrt{3}}{2}$ (S1+S2) $\frac{\sqrt{3}}{3}$ (S1+S2+S3) S1+S2+S3 TYPE2 TYPE3 $\sqrt{P\Sigma^2+Q\Sigma^2}$ QΣ [var] TYPE1 Q1+Q2 Q1+Q2+Q3 TYPE2 $\sqrt{S\Sigma^2 - P\Sigma^2}$ TYPE3 Q1+Q2 Q1+Q2+Q3 [W] [Wh] ΡcΣ Pc1+Pc2 Pc1+Pc2+Pc3 WPΣ WP1+WP2+WP3 WP1+WP2 WP+Σ [Wh] WP+1+WP+2 WP+1+WP+2+WP+3 WP-Σ [Wh] WP-1+WP-2 WP-1+WP-2+WP-3 [Ah] q1**+**q2 q1+q2+q3 qΣ q+Σ [Ah] q+1**+**q+2 q+1+q+2+q+3 [Ah] q-Σ q-1+q-2 q-1+q-2+q-3 . WQΣ [varh] $\frac{1}{N} \sum_{n=1}^{N} |Q\Sigma(n)| \times Time$ $Q\Sigma(n)$ is the nth reactive power Σ function , and N is the number of data updates WSΣ [VAh] $\frac{1}{N} \sum_{n=1}^{N} S\Sigma(n) \times Time$ $S\Sigma(n)$ is the nth apparent power Σ function, and N is the number of data updates λΣ ΡΣ SΣ ØΣ $\cos^{-1} \left(\frac{P\Sigma}{S\Sigma}\right)$ Note1) The instrument's apparent power (S), reactive power (Q), power factor (I), and phase angle (Ø) are calculated using measured values of voltage, current, and active power. (However, reactive power is calculated directly from sampled data when TYPE3 is selected.) Therefore, when distorted waveforms are input, these values may be different from those of other measuring instruments based on different measuring principals. Note 2) The value of Q in the QS calculation is calculated with a preceding minus sign (-) when the current input leads the voltage input, and a plus sign when it lags the voltage input, so the value of QS may be negative.

η [%]	Set a efficiency calculation up to 4
User-defined functions	Create equations combining measurement function symbols, and calculate up to
F1-F20	twenty numerical data.

Waveform Display (WAVE display)

1 3 (,
Waveform display items	Voltage and current from elements 1 through 4
	Motor version torgue and waveform of revolution speed

Accurance

	Voltage/current	Power
[Conditions]	DC:	DC:
	0.05% of reading+0.05% of range	0.05% of reading+0.1% of range
Temperature: 23±5°C	0.1Hz≤f<30Hz	0.1Hz≤f<30Hz
Humidity: 30 to 75%RH	0.1% of reading+0.2% of range	0.2% of reading+0.3% of range
Input waveform:	30Hz≤f<45Hz	30Hz≤f<45Hz
Sine wave	0.03% of reading+0.05% of range	0.05% of reading+0.05% of range
Common mode voltage:	45Hz≤f≤66Hz	45Hz≤f≤66Hz
0 V	0.01% of reading+0.03% of range	0.02% of reading+0.04% of range
Crest factor: 3	66Hz <f≤1khz< td=""><td>66Hz<f≤1khz< td=""></f≤1khz<></td></f≤1khz<>	66Hz <f≤1khz< td=""></f≤1khz<>
Line filter: OFF	0.03% of reading+0.05% of range	0.05% of reading+0.05% of range
λ (power factor): 1	1kHz <f≤10khz< td=""><td>1kHz<f≤10khz< td=""></f≤10khz<></td></f≤10khz<>	1kHz <f≤10khz< td=""></f≤10khz<>
After warm-up.	0.1% of reading+0.05% of range	0.15% of reading+0.1% of range
After zero level	10kHz <f≤50khz< td=""><td>10kHz<f≦50khz< td=""></f≦50khz<></td></f≤50khz<>	10kHz <f≦50khz< td=""></f≦50khz<>
compensation or range	0.3% of reading+0.1% of range	0.3% of reading+0.2% of range
value change while	50kHz <f≤100khz< td=""><td>50kHz<f≤100khz< td=""></f≤100khz<></td></f≤100khz<>	50kHz <f≤100khz< td=""></f≤100khz<>
wired.	0.012×f% of reading+0.2% of range	0.014×f% of reading+0.3% of range
f is frequency	100kHz <f≤500khz< td=""><td>100kHz<f≤500khz< td=""></f≤500khz<></td></f≤500khz<>	100kHz <f≤500khz< td=""></f≤500khz<>
6-month after calibration	0.009×f% of reading+0.5% of range	0.012×f% of reading+1% of range
* These conditions are all accuracy condition in this	500kHz <f≤1mhz< td=""><td>500kHz<f≤1mhz< td=""></f≤1mhz<></td></f≤1mhz<>	500kHz <f≤1mhz< td=""></f≤1mhz<>
section.	(0.022×f-7)% of reading+1% of range	0.048×f-19)% of reading+2% of range

The units of f in the reading error equation are kHz.

- The units of f in the reading error equation are kHz.
 Accuracy of waveform display data, Upk and Ipk Add 3% of range to the accuracy above. However, add 3% of range +5mV for external input(reference value). Effective input range is within ±300%
 Influenced by changes in temperature after zero level correction or range value changes. Add 30pm of range/C to the voltage DC accuracy, 0.2 M/²C to the current DC accuracy, 0.02 mV/²C to the external current DC accuracy, and influence of voltage times influence of current to to the power DC accuracy.
 Influence of self heating due to current input
 When the input signal is current, add 0.00002 x I²% of rdg, and for DC add 0.00002 x I²% of rdg + 0.003 x I²mA to the current and 0.00002 x I²% of rdg, and for DC add 0.00002 x I²% of rdg + 0.003 x I²mA to the current and 0.00002 x I²% of rdg when the signal is current, add 0.00002 x I²% of rdg the 0.05% of rdg when the current and 0.00002 x I²% of rdg when the second accuracy to the data update rate Add 0.05% of rdg when it is 100 ms, and 0.1% of rdg when 50ms.
 Range of guaranteed accuracy by 176 requency, voltage, and current All accuracies between 0.1 Hz and 10 Hz are reference values. If the voltage and power values are reference values.
 If the voltage and power values are reference values.
 If the voltage and power values are reference values.
 If the current exceeds 20 A at DC, 10 Hz–45Hz, or 400 Hz–200 kHz; or if it exceeds 10 A at 200 kHz–500 kHz; or exceeds 5.0 At at 500 kHz–1 MHz, the current and power accuracies are reference values.

reference values

· Accuracy for crest factor 6: Range accuracy of crest factor 3 for two times range of crest factor 6.

Precision Power Analyzer WT3000

	Voltage	e/currer	nt				Po	wer		
Influence of power factor (λ)		_			to 66 H All oth (howe values Appar (0.03+ When Add po $\lambda = 0$))	ent pow Hz rang er frequ ver, the b): ent pow $0.05 \times f($ $0 < \lambda <$ power re	e Jencies Se are Ver reac (kHz))% 1 ading× vever, \$	(tanØ× Ø is the	follows erence (effect	when
Influence of line filter	When cutoff frequen "45 to 66Hz: Add 0.2 Under 45 Hz: Add 0. When cutoff frequen "66Hz or less: Add 0. 66 to 500Hz: Add 0. When cutoff frequen "500Hz or less: Add 500 to 5kHz: Add 0.5	2% of re .5% of r icy is 5. 0.2% of 5% of r icy is 50 0.2% o 5% of r	eading reading 5 kHz reading eading 0 kHz of reading eading	g	"45 to Under When "66Hz 66 to 5 When "500H 500 to	66Hz: / 45 Hz: cutoff f or less 500Hz: cutoff f z or les 5kHz:	Add 0.3 Add 19 requent Add 0 Add 19 requent s: Add Add 19	cy is 50 % of rea % of rea cy is 5.5 .3% of r % of rea cy is 50 0.3% of % of read	ading ding" kHz eading ding" kHz readin ding"	g
Lead/Lag Detection (d (LEAD)/G (LAG) of the phase angle and symbols for the reactive power $Q\Sigma$ calculation) * The symbol shows the lead/lag of each element, and *." indicates leading.	The phase lead and lag are detected correctly when the voltage and current signals are both sine waves, the lead/lag is 50% of the range rating (or 100% for crest factor 6), the frequency is between 20 Hz and 10 kHz, and the phase angle is \pm (5' to 175') or more.									
Temperature coefficient	±0.02% of reading/°	at 5–18	3° or 28-	-40 °C.						
Effective input range	Udc and Idc are 0 to ±130% of the measurement range Urms and Irms are 1 to 130%* of the measurement range (or 2%-130% for crest fractor 6) Umn and Imn are 10 to ±130% of the measurement range Umm and Imm are 10 to ±130%* of the measurement range Power is 0 to ±130%* for DC measurement, 1 to 130%* of the voltage and current range for AC measurement, and up to ±130%* of the power range. However, when the data update rate is 50 ms, 100 ms, 5 sec, 10 sec, or 20 sec, the synchronization source level falls below the input signal of frequency measurement. 140% of the voltage and current range ratingThe accuracy at 110 to 130% of the measurement range is the reading error v1.5.									
Max. display	140% of the voltage									
Min. display	Urms and Irms are up to 0.3% relative to the measurement range (or up to 0.6% for a crest factor of 6). Umn, Urmn, Inn, and Irmn are up to 1% (or 2% for a crest factor of 6). Below that, zero suppress. Current integration value q also depends on the current value.				rrent					
Measurement lower	Data update rate Measurement lower		100ms			-	2s	5s	10s	20s
limit frequency	limit frequency	45Hz	25Hz		10Hz	5Hz	2Hz	0.5Hz	0.2Hz	0.1Hz
Accuracy of apparent power S (reference value)	Voltage accuracy + o			cy						
Accuracy of reactive power Q (reference value)	Accuracy of apparent power + $(\sqrt{(1.0004-\lambda^2)} - \sqrt{(1-\lambda^2)})$ % of range									
Accuracy of power factor λ (reference value)	$\begin{array}{l} \pm \left[(\lambda \! - \! \lambda \! / 1.0002) \! + \left \cos \lambda \! + \right \cos \lambda \! \\ \lambda \! = \! 0\% \! / \! 100) \right\} \left] \pm 1 \mbox{digit} \\ \end{tabular}$	ence of	voltage	e and cu	urrent.					
Accuracy of phase difference Ø (reference value)	± [Ø-cos-1 (λ/1.000 deg λ1digit	2) + sir	n ⁻¹ {(influ	uence o	f power	factor	of powe	er when	λ=0%)	/100}]
One-year accuracy	Add the accuracy of reading error (Six-month after calibration) \times 0.5 to the accuracy six-month after calibration									

Functions

Measurement method Crest factor	Digital multiplication method 3 or 6 (when inputting rated values of the measurement range), and 300 relative to the minimum valid input. However, 1.6 or 3.2 at the maximum range (when inputting rated values of the measurement range), and 160 relative to the minimum valid input.
Measurement interval	 When data update rate is 50 ms, 100 ms, 10 s, or 20 s. Excluding amount of current q given amount of energy Wp and when in DC mode, the measurement interval is set at the zero cross of the reference signal (synchronization source). When data update rate is 250 ms, 500 ms, 1 s, or 2 s Measured using the exponential average relative to the sampling data within the data update rate. When using harmonic display (required/G5 option) The selected FFT data length is the measurement interval.
Wiring	You can select one of the following five wiring settings. 1P2W (single phase, two-wire), 1P3W (single phase, 3 wire), 3P3W (3 phase, 3 wire), 3P4W (3 phase, 4 wire), 3P3W(3V3A) (3 phase, 3 wire, 3 volt/3 amp measurement). However, the number of available wiring settings varies depending on the number of installed input elements. Up to four, or only one, two, or three wiring settings may be available.
Compensation Functions	Efficiency Compensation Compensation of instrument loss during efficiency calculation Wiring Compensation Compensation of instrument loss due to wiring 2 Wattmeter Method Compensation Compensation for 2 wattmeter method
Scaling	When inputting output from external current sensors, VT, or CT, set the current sensor conversion ratio, VT ratio, CT ratio, and power coefficient in the range from 0.0001 to 99999.9999.
Input filter	Line filter or frequency filter settings can be entered.

Averaging	• The average calculations below are performed on the normal measurement parameters of voltage U, current I, power P, apparent power S, reactive power Q. Power factor λ and phase angle Ø are determined by calculating the average of P and S.
	Select exponential or moving averaging. Exponential average
	 Select an attenuation constant of 2, 4, 8, 16, 32, or 64. Moving average
	Select the number of averages from 8, 16, 32, 64, 128, or 256. • The average calculations below are performed on the harmonic display items of voltage U, current I, power P, average the number of the second se
	apparent power S, reactive power Q. Power factor λ is determined by calculating the average of P and Q. Only exponential averaging is performed. Select an attenuation constant of 2, 4, 8, 16, 32 or 64
Data update rate	Select 50 ms, 100 ms, 250 ms, 500 ms, 1 s, 2 s, 5 s, 10 s, or 20 s. However, when the data update rate is 50 ms or 100 ms the display update rate is 250 ms.
Response time	At maximum, two times the data update rate (only during numerical display)
Hold	Holds the data display.
Single	Executes a single measurement during measurement hold.
Zero level compensation/Nul	I Compensates the zero level.
Integration	

Mode	Select a mode of Manual, Standard, Continuous (repeat), Real Time Control Standard, or Real Time Control Continuous (Repeat).
Timer	Integration can be stopped automatically using the integration timer setting. 0000h00m00s-10000h00m00s
Count over	If the count over integration time reaches the maximum integration time (10000 hours), or if the integration value reaches max/min display integration value (±999999 MWh or ±999999 Mah), the elapsed time and value is saved and the operation is stopped.
Accuracy Time accuracy	± (power and current accuracy + time accuracy) 0.02% of reading
Display	

• Numerical display function

Display resolution Number of display items 600000 Select 4, 8, 16, all, single list, or dual list. Waveform display items No. of display rasters 501 Display format Time axis Peak-peak compressed data Range from 0.5 ms–2 s/div. However, it must be 1/10th of the data update rate. Triggers Trigger Type Trigger Mode Edge type Select Auto or Normal. Triggers are turned OFF automatically during integration. Select voltage, current, or external clock for the input to each input element. Trigger Source Select (Rising), (Falling), or (Rising/Falling). Trigger Slope When the trigger source is the voltage or current input to the input elements. Set in the range from the center of the screen to $\pm 100\%$ (top/bottom edge of the screen). Setting resolution: 0.1% Trigger Level When the trigger source is Ext Clk, TTL level. cal axis Zoom Voltage and current input to the waveform vertical axis zoom Vertical axis Zoom input element can be zoomed along the vertical axis. Set in the range of 0.1 to 100 times. ON/OFF can be set for each voltage and current input to the ON/OFF input element. Format Interpolation You can select 1, 2, 3 or 4 splits for the waveform display. Select dot or linear interpolation. Select graticule or cross-grid display. Upper/lower limit (scale value), and waveform label ON/OFF. When you place the cursor on the waveform, the value of that Other display ON/OFF Cursor measurements point is measured. Zoom function No time axis zoom function * Since the sampling frequency is approximately 200 kHz, waveforms that can be accurately reproduced are those of about 10 kHz. Vector Display/Bar Graph Display Vector display of the phase difference in the fundamental waves of voltage and current. Displays the size of each harmonic in a bar graph. Vector display Bar graph display • Trend display Number of measurement channels Up to 16 parameters Displays trends (transitions) in numerical data of the measurement functions in a sequential line graph. Simultaneous display Two windows can be selected (from numerical display. waveform display, bar graph display, or trend display) and displayed in the upper and lower parts of the screen. Saving and Loading Data Settings, waveform display data, numerical data, and screen image data can be saved to media. Saved settings can be loaded from a medium.

WT

Motor Evaluation Function (-MV, Motor Version)

Measurement Function	Method of Determination/Equation
Speed	Method of Determination/Equation When the input signal from the revolution sensor is DC voltage (analog signal) Input voltage from revolution sensor x scaling factor Scaling factor: Number of revolutions per 1 V input voltage When the input signal from the revolution sensor is number of pulses <u>Number of input pulses/minute from revolution</u> sensor No of pulses/revolution
Torque	When the type of input signal from the torque meter is DC voltage (analog signal) Input voltage from torque meter x scaling factor Scaling factor: Torque per 1 V input voltage When the type of input signal from the torque is number of pulses Enter N-m equivalent to upper- and lower-limit frequencies to determine an inclination from these two frequencies, and then multiply the number of pulses.
SyncSp	120 x freq. of the freq. meas. source no. of poles of the motor
Slip[%]	SyncSp-Speed SyncSp ×100
Motor output Pm	$\frac{2\pi \times \text{Speed} \times \text{Torque}}{60}$ ×scaling factor

Revolution signal, torgue signal

	When revolution and torque signals are I	DC voltage (analog input)
	Connector type	Insulated BNC connector
	Input range	1 V,2 V,5 V,10 V,20 V
	Effective input range	0%-±110% of measurement range
	Input resistance	Approximately 1 MΩ
	Continuous maximum allowed input	
	Continuous maximum common mod	
	Accuracy	±(0.1% of reading+0.1% of range)
	Temperature coefficient	±0.03% of range/°C
•	When revolution and torque signals are	
	Connector type	Insulated BNC connector
	Frequency range	2 Hz–200 kHz
	Amplitude input range	±5 Vpeak
	Effective amplitude	1 V (peak-to peak) or less
	Input waveform duty ratio	50%, square wave
	Input resistance	Approximately 1 MΩ
	Continuous maximum common mod	
	Accuracy	±(0.05% of reading+1mHz)

Added Frequency Measurement (/FQ Optional)

Device under measurement	the input elements for measurem FQ) is installed, the frequencies being input to all input elements	nent. If the frequency option (/ of the voltages and currents
Measurement method	Reciprocal method	
Measurement range	Data Update Rate	Measuring Range
	50ms	45Hz≤f≤1MHz
	100ms	25Hz≤f≤1MHz
	250ms	10Hz≤f≤500kHz
	500ms	5Hz≤f≤200kHz
	1s	2.5Hz≤f≤100kHz
	2s	1.5Hz≤f≤50kHz
	5s	0.5Hz≤f≤20kHz
	10s	0.25Hz≤f≤10kHz
	20s	0.15Hz≤f≤5kHz
Accuracy	±0.05% of reading	
	When the input signal levels are	greater than or equal to 25
	mV (current external sensor inpu	it) and 150 mA (current direct
	input) respectively, and the signal	I is greater than or equal to
	30% (0.1 Hz-440 Hz, frequency	filter ON), 10% (440 Hz-500
	kHz), or 30% (500 kHz-1 MHz) o	
	However, when the measuring free	equency is smaller or equal to
	2 times of above lower frequency	
	than or equal to 50%.	1 3 3
	Add 0.05% of reading when current	ent external input is smaller
	than or equal to 50 mV input sign	
	crest factor 6.	

Delta Calculation Function (/DT Optional)

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He

onio Mor

Item	Delta Calculation Setting	Symbols and Meanings
Voltage	Udiff, Idiff	Calculated differential voltage and current
Current	3P3W→3V3A	Line to line voltage and phase current are determined in the calculation for a 3 phase 3 wire connection
	DELTA→STAR	Phase voltage and neutral current are determined in the calculation for 3 phase 3 wire (3V3A) connection
	STAR→DELTA	Line to line voltage and neutral current determined in the calculation for a 3 phase 4 wire connection

ation (ICE Ontio

Harmonic Measurement Function (/G5 Optional)		
Method	PLL synchronization	
Frequency range	PLL source of the fundamental frequency is in the range 10 Hz–440 Hz.	
PLL source	Select voltage, current, or external clock for each input element.	
Word length for FFT Window function	32 bits Rectangular	
Anti-aliasing filter	Set using a line filter (5.5 kHz or 50 kHz)	

Sample rate (sampling frequency), window width, and upper limit of analyzed orders for PLL synchronization. During Harmonic Dis

Builing Harmonic Display			
Fundamental Frequency	Sample Rate	Window Width	Upper Limit of Analyzed orders
10Hz to 20Hz	f*3000	3	100
20Hz to 40Hz	f*1500	6	100
10U = to CCU =	#000	40	400

20Hz to 40Hz	f*1500	6	100
40Hz to 55Hz	f*900	10	100
55Hz to 75Hz	f*750	12	100
75Hz to 150Hz	f*450	20	50
150Hz to 440Hz	f*150	75	15

Accuracy ±(reading error + measurement range error)

• When Line Filter is ON (5.5 kHz)

Sampling Frequency	Voltage Current	Power	
10Hz≤f<30Hz	0.25% of reading+0.3% of range	0.5% of reading+0.4% of range	
30Hz≤f≤66Hz	0.2% of reading+0.15% of range	0.4% of reading+0.15% of range	
66Hz <f≤440hz< td=""><td>0.5% of reading+0.15% of range</td><td>1.2% of reading+0.15% of range</td></f≤440hz<>	0.5% of reading+0.15% of range	1.2% of reading+0.15% of range	
440Hz <f≤1khz< td=""><td>1.2% of reading+0.15% of range</td><td>2% of reading+0.15% of range</td></f≤1khz<>	1.2% of reading+0.15% of range	2% of reading+0.15% of range	
1kHz <f≤2.5khz< td=""><td>2.5% of reading+0.15% of range</td><td>6% of reading+0.2% of range</td></f≤2.5khz<>	2.5% of reading+0.15% of range	6% of reading+0.2% of range	

Power exceeding 440 Hz is a reference value.
 During nth order component input, add (nth order reading) of (n/(m+1))/50% to the (n+m)th order and (n–m)th order.
 Add (n/500)% of reading to nth order components

• When Line Filter is ON (5.5 kHz)

Sampling Frequency	Voltage Current	Power
10Hz≤f<30Hz	0.25% of reading+0.3% of range	0.45% of reading+0.4% of range
30Hz≤f≤440Hz	0.2% of reading+0.15% of range	0.4% of reading+0.15% of range
440Hz <f≤2.5khz< td=""><td>1% of reading+0.15% of range</td><td>2% of reading+0.2% of range</td></f≤2.5khz<>	1% of reading+0.15% of range	2% of reading+0.2% of range
2.5kHz <f≤5khz< td=""><td>2% of reading+0.15% of range</td><td>4% of reading+0.2% of range</td></f≤5khz<>	2% of reading+0.15% of range	4% of reading+0.2% of range
5kHz <f≤7.5khz< td=""><td>3.5% of reading+0.15% of range</td><td>6.5% of reading+0.2% of range</td></f≤7.5khz<>	3.5% of reading+0.15% of range	6.5% of reading+0.2% of range

Power exceeding 440 Hz is a reference value.
 During nth order component input, add (nth order reading) of (n/(m+1))/50% to the (n+m)th order and (n-m)th order.
 Add (n/500)% of reading to nth order components

• When Line Filter is OFF

Sampling Frequency	Voltage Current	Power
10Hz≤f<30Hz	0.15% of reading+0.3% of range	0.25% of reading+0.4% of range
30Hz≤f≤440Hz	0.1% of reading+0.15% of range	0.2% of reading+0.15% of range
440Hz <f≤2.5khz< td=""><td>0.6% of reading+0.15% of range</td><td>1.2% of reading+0.2% of range</td></f≤2.5khz<>	0.6% of reading+0.15% of range	1.2% of reading+0.2% of range
2.5kHz <f≤5khz< td=""><td>1.6% of reading+0.15% of range</td><td>3.2% of reading+0.2% of range</td></f≤5khz<>	1.6% of reading+0.15% of range	3.2% of reading+0.2% of range
5kHz <f≤7.5khz< td=""><td>2.5% of reading+0.15% of range</td><td>5% of reading+0.2% of range</td></f≤7.5khz<>	2.5% of reading+0.15% of range	5% of reading+0.2% of range

Power exceeding 440 Hz is a reference value.
 During nth order component input, add (nth order reading) of (n/(m+1))/50% to the (n+m)th order and (n–m)th order.
 Add (n/500)% of reading to nth order components

D/A Output (/DA Optional)

Output voltage ±5 V FS (max. Update rate Same as the o However, sele	wo times the data update rate. approximately \pm 7.5 V) for each rated value lata update rate on the main unit. ct 10 ms or 20 ms during high speed D/A output. response time is up to two times the display
Number of outputs 20 channels (e	a given measurement function + 0.1% of FS)
$\begin{array}{llllllllllllllllllllllllllllllllllll$	^{/o} C
Frequency D/A output Approx. 7.5 V 2.5 V 0.5 V	Displayed value
0.5Hž 1Hz 10Hz 100H Integrated Value D/A output	Hz 1kHz 10kHz 100kHz 1MHz
Approx. 7.0 V 5.0V	Rated input
t0:Rated time of integrated D/A outp	ut for manual integration mode to
specified time of timer for normal (continuous) integration modes	integration and repetitive D/A output ₄
Other Items Displayed Value Output 140% Approx.7.0 V 100% Approx.7.0 V 100% 5.0 V 0.0 V 0.0 V 0.0 V -100% 5.0 V -100% 5.0 V -140% Approx.7.0 V -140% Approx.7.0 V -140% Approx.7.0 V -140% Approx.7.0 V Note that PF and deg are not output beyond the range. If an error occurs, approximately ±7.5 V are output. 0' to 360° are output at 0.0 S.0 V; LAG180° to LEAD18 output at -5.0 V to 5.0 V. Vici 5.0 V. Vici 5.0 V. Vici 5.0 V. Vici 5.0 V.	:

Built-in Printer (/B5 Optional)

Printing method Dot density Paper width Effective recording width Recorded information Thermal line-dot 8 dots/mm 112 mm 104 mm Screenshots, list of measured values, harmonic bar graph printouts, settings

Precision Power Analyzer WT3000

Serial (RS-232) Interf	iace (/C2 Optional)
Connector type Electrical specifications Connection type Communication mode Synchronization method Baud rate	9-pin D-Sub (plug) Conforms with EIA-574 (EIA-232 (RS-232) standard for 9-pin) Point-to-point Full duplex Start-stop synchronization Select from the following. 1200,2400,4800,9600,19200 bps
RGB Video Signal (V	GA) Output Section (/V1 Optional)
Connector type Output format	15-pin D-Sub (receptacle) VGA compatible
Ethernet Communica	ations (/C7 Optional) Sales announcement
	image data can be saved to an FTP server on the network. You can load settings saved on an FTP server. You can access the instrument from a PC or workstation

External I/O

I/O Section for Master/Slav Connector type I/O level Output logic Measurement start delay time Output hold time Input logic Minimum pulse width Input delay time	e Synchronization Signals BNC connector: Both slave and master TTL: Same for both slave and master Negative logic, falling edge: Applies to master Within (100 ns + 1 sample rate): Applies to master Low level, 200 ns or less: Applies to master Negative logic, falling edge: Applies to slave Low level, 200 ns or less: Applies to slave Within (100 ns + 1 sample rate): Applies to slave
Frequency range Input waveform	n BNC connector TTL source as the Ext Clk of normal measurement. Same as the measurement range for frequency measurement. 50% duty ratio square wave he Ext Clk of harmonic measurement. 10 Hz to 2.5 kHz 50% duty ratio square wave
For Triggers Minimum pulse width Trigger delay time	1 μs Within (1 μs + 1 sample rate)
PC Card Interface	TYPE II (Flash ATA card)
GP-IB Interface Encoding Mode Address Clear remote mode	Use one of the following by NATIONAL INSTRUMENTS: • AT-GPIB • PCI-GPIB and PCI-GPIB+ • PCMCIA-GPIB and PCMCIA-GPIB+ Use driver NI-488.2M version 1.60 or later. Conforms electrically and mechanically to IEEE St'd 488-1978 (JIS C 1901-1987). Functional specification SH1, AH1, T6, L4, SR1, RL1, PP0, DC1, DT1, and CO. Conforms to protocol IEEE St'd 488.2-1987. ISO (ASCII) Addressable mode 0–30 Remote mode can be cleared using the LOCAL key (except during Local Lockout).
General Specification	s

Warm-up time	Approximately thirty minutes.
Operating temperature:	5–40°C
Operating humidity:	20-80% (when printer not used), 35 to 80% RH (when printer
	is used)
	(No condensation may be present)
Operating altitude	2000 m or less
Storage environment:	 -25–60°C (no condensation may be present)
Storage humidity:	20 to 80% RH (no condensation)
Rated supply voltage	100–240 VAC
Allowed supply voltage fluctu	ation range 90–264 VAC
Rated supply frequency	50/60 Hz
Allowed supply frequency flu	ctuation 48 to 63 Hz
Maximum power consumption	n 150 VA (when using built-in printer)
Weight	Approximately 15 kg (including main unit, 4 input elements,
-	and options)
Battery backup	Setup information and internal clock are backed up with the lithium battery