



# Virtual HMI User Instructions

ISC CAM AIM Technology

Version 1.1

29 August 2023

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  - Equipment
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# Intended design and use of Virtual HMI

- Virtual HMI facilitates the interaction of non-controls experts with the Intralox equipment to:
  - commission,
  - adjust key operating parameters,
  - communicate faults,
  - communicate basic operating log data.

# How to use this document

- Additional documents from the Intralox User Manual
  - Mechanical drawing of Intralox Equipment
    - Dimensions of Intralox equipment and position of the components
  - Functional layout drawing of Intralox equipment
    - Application information: product trajectories, belt speeds, min product gaps,
  - ISC Interlocks Document
  - ISC Troubleshooting Guide

# Good to know

- Default IP Address: 192.168.1.254
- IP address displayed on the HMI updates only after reboot of the ISC CAM (power off/on).
- All parameters/values displayed on HMI are available on the ethernet network
- Click on “Submit” button to implement changes on the ‘fly’.
- Units: SI
- IDL: Intralox Divert Logic

# Connection to the Virtual HMI

# How to connect to the Virtual HMI?

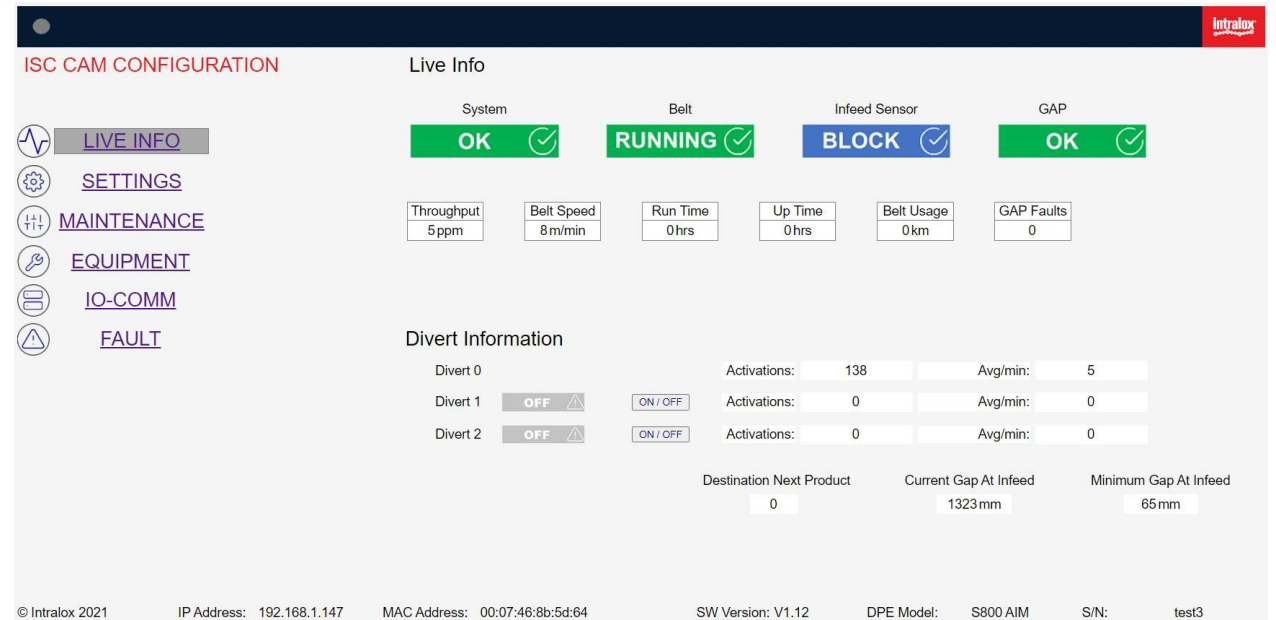
- Connect with a laptop to the ethernet network of the ISC CAM
  - If the ISC CAM is not connected to any ethernet, connect directly to the ethernet port of the ISC CAM.
- Write the IP address of the ISC CAM on the navigation bar of an internet browser such as Microsoft Edge, Google Chrome, Mozilla Firefox or similar.
  - If the IP address of the ISC CAM is unknown, please request it to the responsible/manager of PLC network or use the Intralox Service Tool available on [www.Intralox.com/isccam](http://www.Intralox.com/isccam)
  - Default IP address: 192.168.1.254

# HMI Overview



# Number of pages & high level Description

- The Virtual HMI has 6 pages
  1. Live: landing page
  2. Settings
  3. Maintenance
  4. Equipment
  5. IO-Communication
  6. Faults



# Interface Overview

The screenshot displays the Intralox ISC CAM CONFIGURATION interface. It features a navigation panel on the left (callout 1), a live information section at the top (callout 4), a bottom information bar (callout 2), and a live bit indicator (callout 3).

**Navigation Panel (1):** A vertical menu on the left side containing icons and links for LIVE INFO, SETTINGS, MAINTENANCE, EQUIPMENT, IO-COMM, and FAULT.

**Live Info (4):** A section at the top right displaying system status. It includes a 'Live Info' header and four status indicators: System (OK), Belt (RUNNING), Infeed Sensor (BLOCK), and GAP (OK). Below these are six data boxes: Throughput (5 ppm), Belt Speed (8 m/min), Run Time (0 hrs), Up Time (0 hrs), Belt Usage (0 km), and GAP Faults (0).

**Divert Information:** A section below the Live Info, showing data for three divert units. Each unit has an 'ON / OFF' toggle, 'Activations' count, and 'Avg/min' rate.

Divert	Status	Activations	Avg/min
Divert 0	ON	138	5
Divert 1	OFF	0	0
Divert 2	OFF	0	0

**Bottom Information Bar (2):** A horizontal bar at the bottom containing system information: © Intralox 2021, IP Address: 192.168.1.147, MAC Address: 00:07:46:8b:5d:64, SW Version: V1.12, DPE Model: S800 AIM, S/N: test3.

**Live bit (3):** A small red indicator in the top right corner of the interface.

## 1. Navigation pannel

- Live Info
- Settings
- Maintenance
- Equipment
- IO-COMM
- Fault

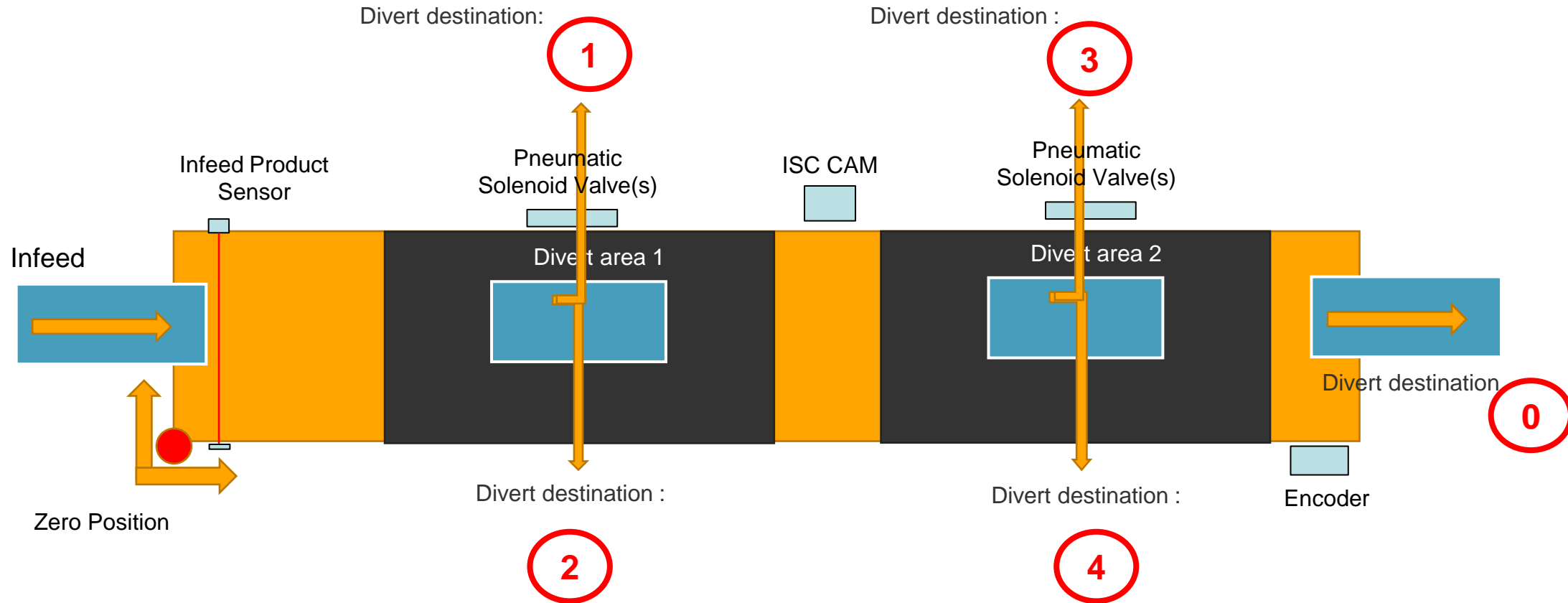
## 2. Bottom Information Bar

1. IP Address of ISC CAM
2. MAC Address: electronic unique identifier
3. SW Version: Intralox Divert Logic Version
4. DPE Model: Intralox Product Family
5. S/N: serial number of the Intralox equipment

## 3. Page Unique Information

## 4. Live bit

# Intralox Sorters




# 1. Live page


# End in Mind


- Provide an overview of the status of Intralox equipment using real-time operating data. The data is generated from the field components:
  - Infeed product sensor,
  - encoder,
  - solenoids valves
- 'Read only' page
- Intended users: Any user such as equipment operator, controls engineers, maintenance tech


# Live Info – Indicators





ISC CAM CONFIGURATION


 [LIVE INFO](#)

 [SETTINGS](#)

 [MAINTENANCE](#)


 [EQUIPMENT](#)

 [IO-COMM](#)


 [FAULT](#)

Live Info


System

OK 


Belt

RUNNING 

Infeed Sensor



BLOCK 

GAP

OK 

Throughput	Belt Speed	Run Time	Up Time	Belt Usage	GAP Faults
5ppm	8 m/min	0hrs	0hrs	0 km	0

Divert Information

Divert 0		Activations:	138	Avg/min:	5
Divert 1	<div>OFF </div> <div>ON / OFF</div>	Activations:	0	Avg/min:	0
Divert 2	<div>OFF </div> <div>ON / OFF</div>	Activations:	0	Avg/min:	0

Destination Next Product

0

Current Gap At Infeed

1323 mm

Minimum Gap At Infeed

65 mm

© Intralox 2021

IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

DPE Model: S800 AIM

S/N: test3

## System

General status of the system to run

- Belt**

Status of the belt.

- Infeed Sensor**


Status infeed Product Sensor.

- Gap**


Status of gap between 2 consecutive products measured by the infeed product sensor. See page faults for definition of GAP not “OK”.


Gap shorter than “Min Gap at Infeed” triggers fault signal to PLC. See troubleshooting guideline.


# Live Info – Indicators





ISC CAM CONFIGURATION


 LIVE INFO

 SETTINGS

 MAINTENANCE


 EQUIPMENT

 IO-COMM


 FAULT

Live Info


System

OK 


Belt

RUNNING 

Infeed Sensor

BLOCK 

GAP

OK 

Throughput

5 ppm

Belt Speed

8 m/min

Run Time

0 hrs

Up Time

0 hrs



Belt Usage

0 km

GAP Faults

0

Divert Information

Divert 0			Activations:	138	Avg/min:	5
Divert 1	OFF 	ON / OFF	Activations:	0	Avg/min:	0
Divert 2	OFF 	ON / OFF	Activations:	0	Avg/min:	0

Destination Next Product

0

Current Gap At Infeed

1323 mm

Minimum Gap At Infeed

65 mm

© Intralox 2021

IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

DPE Model: S800 AIM

S/N: test3

## Throughput

Number of products crossing the infeed product sensor in the last minute, updated every minute (not instantaneously)

- **Belt Speed**

Linear belt speed.

- **(Belt) Run Time**

Time Duration since ISC CAM is powered on first time. It only increases when the belt is moving (receiving encoder pulses)

- **Up Time**

Time duration since the ISC CAM was last time powered on.

- **Belt Usage**

Total distance travelled by the belt since first encoder pulse.

- **Gap Fault**

Total number of 'Gap Not OK' since the first encoder pulse. See page faults for definition of GAP not "OK".

# Live Info – Divert Information

ISC CAM CONFIGURATION

Live Info

System: OK

Belt: RUNNING

Infeed Sensor: BLOCK

GAP: OK

Throughput	Belt Speed	Run Time	Up Time	Belt Usage	GAP Faults
5 ppm	8 m/min	0 hrs	0 hrs	0 km	0

Divert Information

Divert	Status	ON / OFF	Activations	Avg/min
Divert 0	ON	ON / OFF	138	5
Divert 1	OFF	ON / OFF	0	0
Divert 2	OFF	ON / OFF	0	0

Destination Next Product	Current Gap At Infeed	Minimum Gap At Infeed
0	1323 mm	65 mm

© Intralox 2021 IP Address: 192.168.1.147 MAC Address: 00:07:46:8b:5d:64 SW Version: V1.12 DPE Model: S800 AIM S/N: test3

- **Divert Number**

Zone counting starts from infeed of the Intralox equipment

- **ON/OFF button**

ON: zone is available to divert products

OFF: zone is not available to divert products

The ISC CAM would not activate this exit even if the LINE PLC indicates it.

Use the “OFF” button when a zone needs to be temporarily unavailable. Ex: maintenance task.

- **Activations**

Total number of activations of the divert since first encoder pulse received by the ISC CAM (absolute number)

Avg per Minute: products crossing the infeed product sensor in the last minute, update every 60 seconds

- **Destination Next Product**

Destination assigned to next product crossing the Infeed Product Sensor.

- **Current Gap at Infeed**

Gap measured by Infeed Product sensor between 2 products. Max gap displayed is the length of the Intralox conveyor.

- **Minimal Gap at Infeed**

Minimal required gap between 2 products for the Intralox equipment to operate correctly. Functional Layout and ISC Troubleshooting guideline.



## 2. Settings Page

# Setting: End in Mind

- Provides the ability to modify key operating parameters (settings) of the Intralox equipment to optimise the trajectory of products.
- 'Read and Write'. Option to import and export 'Application setting files'
- Intended users
  - Technical operators looking for adjusting the performance of the Intralox equipment. Ex. maintenance tech

# Setting General

ISC CAM CONFIGURATION

**Settings**

Select File:  No file chosen  Filename:

Status: machine constants file loaded

**General Settings**

Internal Count 0:  Internal Count 1:  Internal Count 2:

**General Settings**

PE Position Offset:  mm Default Destination:

Min Product Length:  mm Retain Divert:

**Area 1**

Divert Offset:  mm

Activation Delay Override:  ms

Deactivation Delay Override:  ms

**Area 2**

Divert Offset:  mm

Activation Delay Override:  ms

Deactivation Delay Override:  ms

**Click "Submit" button to implement changes**

© Intralox 2021 IP Address: 192.168.1.147 MAC Address: 00:07:46:8b:5d:64 SW Version: V1.12 DPE Model: S800 AIM S/N: test3

- **Import Setting Button**

Import to the ISC CAM backup application setting files to (extension ".apl"). Ex: factory setting

- **Export Data Button**

Export application setting files to generate backup

- **Internal Count 0, 1 and 2**

Slugs/Train functionality. Number of products allocated to divert #. Only applicable when ISC CAM is working in "Internal Model", see HMI Page "Equipment".

- **Min Product Length**

Minimum distance the infeed PE signal must be stable, to be accepted as product read. Distance shorter will be considered 'noise' or "product debris" such as tape of shrink plastic.

- **PE Position OffSet**

Infeed Product Sensor distance from the Zero Position. See Mechanical Drawing.

- **Default Destination**

Destination of product when no signal is received from the Line PLC (external mode) or no slugs/train function is set (internal mode)

- **Retain Divert**

Divert activation changes when product needs change direction

# Setting General (AIM)

ISC CAM CONFIGURATION

Settings

Select File:  No file chosen  Filename:

Status: machine constants file loaded

General Settings

Internal Count 0:  Internal Count 1:  Internal Count 2:

General Settings

PE Position Offset:  mm Default Destination:

Min Product Length:  mm Retain Divert:

Area 1

Divert Offset:  mm

Activation Delay Override:  ms

Deactivation Delay Override:  ms

Area 2

Divert Offset:  mm

Activation Delay Override:  ms

Deactivation Delay Override:  ms

Click "Submit" button to implement changes

© Intralox 2021 IP Address: 192.168.1.147 MAC Address: 00:07:46:8b:5d:64 SW Version: V1.12 DPE Model: S800 AIM S/N: test3

- **Divert OffSet**

(Start of ) divert area distance from the position defined by Intralox. See Mechanical Drawing of position.

- **Activation Delay Override**

This value considers mechanical delays of the activation system of the Intralox equipment from product detection until product starts moving on the belt.

- **SUBMIT BUTTON**

Click button for making the modifications on the IDL effective.


### **3. Maintenance Page**


# End in Mind


- Display the 'equipment log' with absolute counter values
- 'Read only', ability to export counter files.
- Intended users: maintenance.


# Maintenance


ISC CAM CONFIGURATION


 [LIVE INFO](#)

 [SETTINGS](#)

 [MAINTENANCE](#)

 [EQUIPMENT](#)

 [IO-COMM](#)

 [FAULT](#)

Maintenance

Filename:  [Save Counters](#)

Status: machine constants file loaded

Counters			
Up Time:	0 hrs	Belt Runtime:	0 hrs
Product Count:	157	GAP Fault Count:	0
Divert 1 Count:	0	Divert 2 Count:	0
		Belt Usage:	0 km
		Divert 0 Count:	169

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IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

DPE Model: S7050 ARB

S/N: test4

## Up time

Time elapsed since the ISC CAM was powered on. It resets to zero when the ISC CAM is powered off.

## Belt Run Time

Time elapsed since the ISC CAM received the first encoder pulse. It only increments when the ISC CAM receives encoder pluses. It never resets to zero

## Belt Usage

Total distance travelled by the belt since first encoder pulse. It never resets to zero

## Product Count

Total count number of products that passed the infeed product sensor (absolute value) since first encoder pulse.

## GAP Fault Count

Total number of 'Gap Not OK' since the first encoder pulse. See page faults for definition of GAP not "OK".

## Divert 0, 1, 2

Total number of activations of each divert since first encoder pulse .

## Save Counters BUTTON

Click button to export the counter values. File extension is 'cnt' and requires Intralox tool to make it readable.

## 4. Equipment Page



# End in Mind

- Ability to modify key operating parameters (settings) of the Intralox equipment to optimise the trajectory of products.
- ‘Read and write’
  - Read: read the Intralox equipment mechanical dimensions relevant for the automation of the carryway
  - Write: upload files with the mechanical dimensions of the Intralox equipment
- Intended users
  - Controls engineers integrating the ISC CAM into the Line network (communication)
  - Maintenance operators troubleshooting
- See Functional Layout and Mechanical Drawing

# Equipment -Application Data

ISC CAM CONFIGURATION

**Equipment**

Application Data

Application: Switch Activation Type: R&R 1-3 Belt Type: S7050 ARB Minimum GAP: 65 mm

Hardwired Signal: Disable Run Mode: Internal Sensor Mode: Light On Fault Override: 0

Belt Data

Conveyor Length: 1465 mm Belt Width: 2007 mm Sprocket Teeth: 10 Pitch: 81 mm

Encoder Resolution: 64 Belt Traveled/Pulse: 3.96 mm/P Maximum Speed: 90 m/min Minimum Speed: 0 m/min

Divert Data

Divert Area Count: 1 Zone Length: 64 mm Inf. Sensor Count: 1 PE Position: 135

Valve Placement: Left

Area 1

Position: 126 mm Activation Delay: 55 ms

Area 2

Position: 1547 mm Activation Delay: 22 ms

Zone Count: 7 Zone Count: 2

Submit

© Intralox 2021 IP Address: 192.168.1.147 MAC Address: 00:07:46:8b:5d:64 SW Version: V1.12 DPE Model: S7050 ARB S/N: test4

- **Application**

Type of functionality that the Intralox equipment is performing when diverting products: Sorter or Switch

- **Activation Type**

Type of mechanical activation mechanism used for engaging with Intralox belt for diverting products: PopUp, RnR or AIM

- **Belt Type**

Intralox Belt series used in the Intralox equipment.

- **Minimum Gap**

Minimum distance between products at the infeed of Intralox See Functional Layout

- **Hardware Signal**

Selections: enable or disable.

Hardwire signal “enable” results that ONLY the 1st divert reacts to the discrete signal of 24VDC to activate. The discrete signal has priority over the ethernet signal. Use hardware signal when the Intralox equipment has a high-speed reject

- **Run Mode**

Selections: Internal or external

Internal Mode: ISC CAM operates in autonomous mode with an internal counter for diverting products

External Mode: ISC CAM requires the input signal from the Line PLC for diverting (or not) each product.

- **Sensor Mode**

Selection: Light On / Dark On

Applicable to infeed product sensor. Use only for replacement

- **Fault Override**

Mask - Selection: number, overrides faults. See HMI Page “Faults”.

# Equipment –Belt Data

ISC CAM CONFIGURATION

**EQUIPMENT**

**Equipment**

Select File:  No file chosen

Status: machine constants file loaded

**Application Data**

Application:  Activation Type:  Belt Type:  Minimum GAP:

Hardwired Signal:  Run Mode:  Sensor Mode:  Fault Override:

**Belt Data**

Conveyor Length:  Belt Width:  Sprocket Teeth:  Pitch:

Encoder Resolution:  Belt Traveled/Pulse:  Maximum Speed:  Minimum Speed:

**Divert Data**

Divert Area Count:  Zone Length:  Inf. Sensor Count:  PE Position:

Valve Placement:

**Area 1**

Position:  Activation Delay:

**Area 2**

Position:  Activation Delay:

Zone Count:  Zone Count:

© Intralox 2021 IP Address: 192.168.1.147 MAC Address: 00:07:46:8b:5d:64 SW Version: V1.12 DPE Model: S7050 ARB S/N: test4

Click "Submit"  
button to implement  
changes

- **Conveyor Length**  
Length in [mm] of the frame of the Intralox equipment.
- **Width**  
Belt width
- **Sprocket Teeth**  
Number of teeth of the sprocket
- **Pitch**  
Length of the module of the belt.
- **Encoder Resolution**  
Number of pulses generated by the encoder per revolution. Standard = 64 pulse/rev
- **Belt Travel/pulse**  
Conversion of the belt travel distance in [1/10mm] for each encoder pulse. Dependant of the belt pitch
- **Maximum Speed**  
Recommended Maximum belt speed of the Intralox equipment. Functional Layout.
- **Minimum Speed**  
Recommended minimum belt speed of Intralox equipment. Functional Layout

# Equipment – DARB Divert Data

ISC CAM CONFIGURATION

Machine

Select File:  No file chosen

Status: no file loaded

Application Data

Application:  Activation Type:  Belt Type:  Minimum GAP:

Hardwired Signal:  Run Mode:  Sensor Mode:  Fault Override:

Belt Data

Conveyor Length:  Belt Width:  Sprocket Teeth:  Pitch:

Encoder Resolution:  Belt Traveled/Pulse:  Maximum Speed:  Minimum Speed:

Divert Data

Divert Area Count:  Zone Length:  Inf. Sensor Count:  PE Position:

Area 1

Position:  Activation Delay:

Zone Count:

Area 2

Position:  Activation Delay:

Zone Count:

© Intralox 2021 IP Address: 192.168.1.254 MAC Address: 00:07:46:8c:bd:f7 SW Version: V1.0 DPE Model: S4500 DARB S/N: 2296406 E2021DSW332

- **Divert Area Count**

Area # starts from infeed of the Intralox equipment.  
See image in next page.

- **Zone Length**

Length of the divert area.

- **Inf Sensor Count**

Number of Infeed product sensor.

- **PE Position**

Infeed Product Sensor distance from the Zero Position.

Click "Submit"  
button to implement  
changes

# Equipment

ISC CAM CONFIGURATION

LIVE INFO

SETTINGS

MAINTENANCE

**EQUIPMENT**

IO-COMM

FAULT

Equipment

Select File:  No file chosen   
Status: machine constants file loaded

Application Data

Application: Sorter

Activation Type: AIM Switch block

Belt Type: S800 AIM

Minimum GAP: 65 mm

Hardwired Signal:

Run Mode:

Sensor Mode:

Fault Override:

Belt Data

Conveyor Length: 1587 mm

Belt Width: 660 mm

Sprocket Teeth: 8

Pitch: 50.8 mm

Encoder Resolution: 64

Belt Traveled/Pulse: 3.96 mm/P

Maximum Speed: 60 m/min

Minimum Speed: 0 m/min

Divert Data

Divert Area Count: 2

Zone Length: 1320 mm

Inf. Sensor Count: 1

PE Position: 85

Area 1

Position: 85 mm

Activation Delay: 34 ms

Peg Sensor Offset: 45 mm

Area 2

Position: 685 mm

Activation Delay: 12 ms

Peg Sensor Offset: 45 mm

Deactivation Delay: 34 ms

Deactivation Delay: 12 ms

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IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

DPE Model: S800 AIM

S/N: test3

Click "Submit"  
button to implement  
changes

- Divert Area Count  
Area # starts from infeed of the Intralox equipment. See image in next page.
- Zone Length  
Length of the divert zone
- Inf Sensor Count  
Number of Infeed product sensor.
- PE Position  
Infeed Product Sensor distance from the Zero Position.

# Equipment

ISC CAM CONFIGURATION

LIVE INFO

SETTINGS

MAINTENANCE

**EQUIPMENT**

IO-COMM

FAULT

Equipment

Select File:  No file chosen

Status: machine constants file loaded

Application Data

Application: Sorter

Activation Type: AIM Switch block

Belt Type: S800 AIM

Minimum GAP: 65 mm

Hardwired Signal:

Run Mode:

Sensor Mode:

Fault Override:

Belt Data

Conveyor Length: 1587 mm

Belt Width: 660 mm

Sprocket Teeth: 8

Pitch: 50.8 mm

Encoder Resolution: 64

Belt Traveled/Pulse: 3.96 mm/P

Maximum Speed: 60 m/min

Minimum Speed: 0 m/min

Divert Data

Divert Area Count: 2

Zone Length: 1320 mm

Inf. Sensor Count: 1

PE Position: 85

Area 1

Area 2

Position: 85 mm

Activation Delay: 34 ms

Position: 685 mm

Activation Delay: 12 ms

Peg Sensor Offset: 45 mm

Deactivation Delay: 34 ms

Peg Sensor Offset: 45 mm

Deactivation Delay: 12 ms

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IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

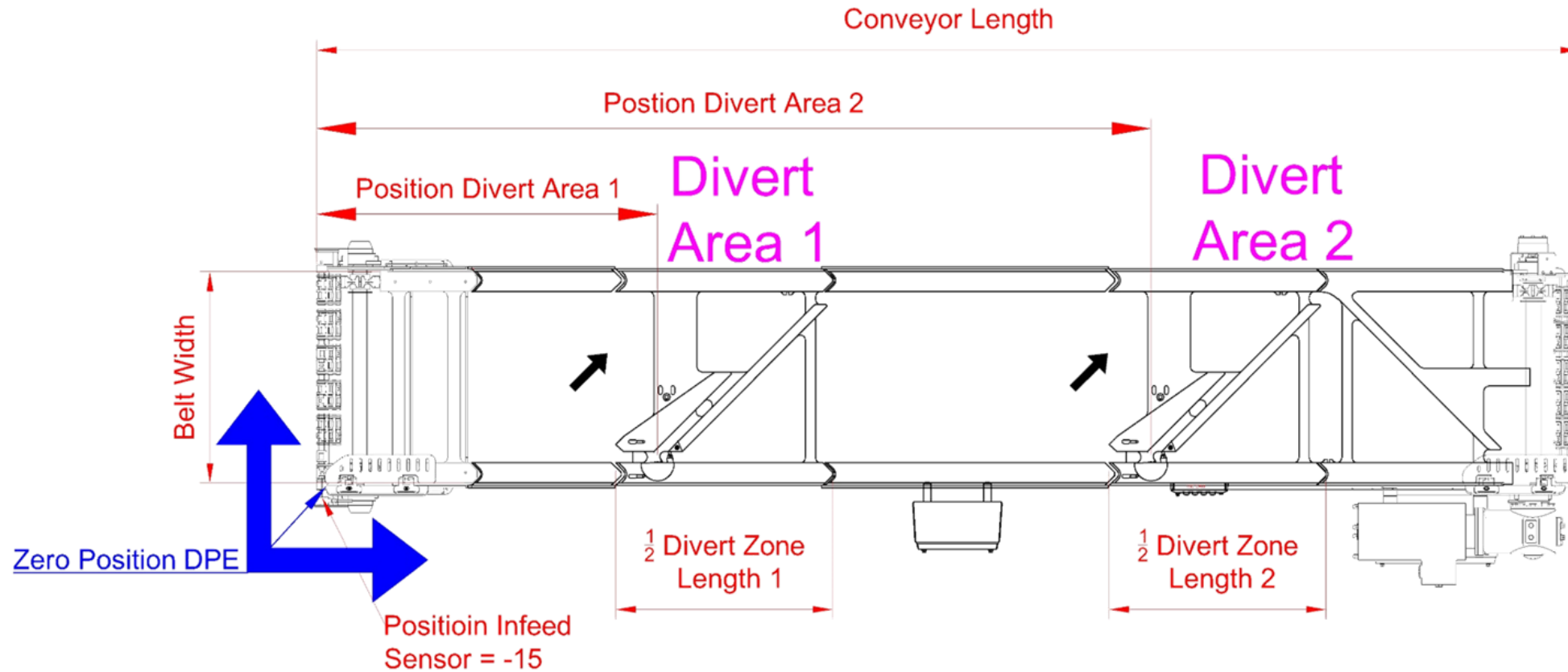
DPE Model: S800 AIM

S/N: test3

- **Position**  
(Start of) divert area distance from the Zero Position.
- **Activation Delay**  
Standard mechanical activation delay between a signal is received by the ISC CAM and the product starts moving on the belt.
- **Peg Sensor OffSet**  
Peg sensor distance from Zero Position
- **SUBMIT BUTTON**  
Push button for making the modifications in the IDL effective.
- **NOTE: Area 2 is optional**

Click "Submit"  
button to implement  
changes

# Appendix 4: AIM Application





# 5.IO-COMM Page



# End in Mind

- Detail the communication status between the ISC CAM with the field components and the line PLC. Please refer to the ISC CAM Interlocks Document for additional information and ISC Troubleshooting document actions
- ‘read only’
- Intended users
  - Line control engineers

# IO-COMM Status

ISC CAM CONFIGURATION

LIVE INFO

SETTINGS

MAINTENANCE

EQUIPMENT

**IO-COMM**

FAULT

IO & Communication Status

Hardware Input Status

Encoder: Negative    Infeed PE: BLOCK    Reject Signal: OFF    Peg Sensor 1: CLEAR    Peg Sensor 2: CLEAR

IO-Link Output Status

Output Port1 Value: 0    Output Port2 Value: 0    Valve 1: OFF    Valve 2: OFF

Communication Input Words (From PLC to ISC)

WORD 00: 0    WORD 01: 0    WORD 02: 0    WORD 03: 0    WORD 04: 0    WORD 05: 0  
WORD 06: 0    WORD 07: 0    WORD 08: 0    WORD 09: 0    WORD 10: 0    WORD 11: 0  
WORD 12: 0    WORD 13: 0    WORD 14: 0    WORD 15: 0

Communication Output Words (From ISC To PLC)

WORD 00: 18    WORD 01: 65535    WORD 02: 0    WORD 03: 1    WORD 04: 4    WORD 05: 15  
WORD 06: 233    WORD 07: 0    WORD 08: 0    WORD 09: 0    WORD 10: 20    WORD 11: 0  
WORD 12: 0    WORD 13: 0    WORD 14: 0    WORD 15: 0

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IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12


DPE Model: S7050 ARB


S/N: test4


- **Encoder**  
Status of encoder, blinking with each pulse
- **Infeed PE**  
Status of infeed product sensor
- **Reject Signal**  
Status of hardwire reject signal
- **Peg Sensor 1**  
Only applicable for AIM applications. Status of peg sensor of divert 1, blinking with each peg passing the beam the peg sensor (belt has to move)
- **Peg Sensor 2**  
Only applicable for AIM applications. Status of peg sensor of divert 2, blinking with each peg passing the beam the peg sensor (belt has to move)


# IO-COMM Status


ISC CAM CONFIGURATION


 LIVE INFO

 SETTINGS

 MAINTENANCE

 EQUIPMENT

 IO-COMM

 FAULT

IO & Communication Status

Hardware Input Status

Encoder: Negative Infeed PE: BLOCK Reject Signal: OFF Peg Sensor 1: CLEAR Peg Sensor 2: CLEAR

IO-Link Output Status

Output Port1 Value: 0 Output Port2 Value: 0 Valve 1: OFF Valve 2: OFF

Hardwired Output Status

Communication Input Words (From PLC to ISC)

WORD 00: 0 WORD 01: 0 WORD 02: 0 WORD 03: 0 WORD 04: 0 WORD 05: 0

WORD 06: 0 WORD 07: 0 WORD 08: 0 WORD 09: 0 WORD 10: 0 WORD 11: 0

WORD 12: 0 WORD 13: 0 WORD 14: 0 WORD 15: 0

Communication Output Words (From ISC To PLC)

WORD 00: 18 WORD 01: 65535 WORD 02: 0 WORD 03: 1 WORD 04: 4 WORD 05: 15

WORD 06: 233 WORD 07: 0 WORD 08: 0 WORD 09: 0 WORD 10: 20 WORD 11: 0

WORD 12: 0 WORD 13: 0 WORD 14: 0 WORD 15: 0

© Intralox 2021

IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

DPE Model: S7050 ARB

S/N: test4

- **IO-Link Output Status**

- Out Port 1 valve**

- Only applicable to RnR technology. Status of valve bank.

- Out Port 2 valve (optional)**

- Only applicable to RnR technology. Status of valve bank.

- **Hardware Output Status**

- Valve 1**

- Only applicable to Popup and AIM technology

- OFF: valve is off

- ON: valve is on.

- Valve 2 (optional)**

- Only applicable to Popup and AIM technology

- OFF: valve is off

- ON: valve is on.

# IO-COMM Input Words

ISC CAM CONFIGURATION

LIVE INFO

SETTINGS

MAINTENANCE

EQUIPMENT

**IO-COMM**

FAULT

IO & Communication Status

Hardware Input Status

Encoder: Negative Infeed PE: BLOCK Reject Signal: OFF Peg Sensor 1: CLEAR Peg Sensor 2: CLEAR

IO-Link Output Status

Output Port1 Value: 0 Output Port2 Value: 0

Hardwired Output Status

Valve 1: OFF Valve 2: OFF

Communication Input Words (From PLC to ISC)

WORD 00: 0 WORD 01: 0 WORD 02: 0 WORD 03: 0 WORD 04: 0 WORD 05: 0

WORD 06: 0 WORD 07: 0 WORD 08: 0 WORD 09: 0 WORD 10: 0 WORD 11: 0

WORD 12: 0 WORD 13: 0 WORD 14: 0 WORD 15: 0

Communication Output Words (From ISC To PLC)

WORD 00: 18 WORD 01: 65535 WORD 02: 0 WORD 03: 1 WORD 04: 4 WORD 05: 15

WORD 06: 233 WORD 07: 0 WORD 08: 0 WORD 09: 0 WORD 10: 20 WORD 11: 0

WORD 12: 0 WORD 13: 0 WORD 14: 0 WORD 15: 0

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IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

DPE Model: S7050 ARB

S/N: test4

1. Words sent by the ISC CAM to the Line PLC through the ethernet network
2. See ISC CAM Interlocks file for details

# IO-COMM Output Words

ISC CAM CONFIGURATION

LIVE INFO

SETTINGS

MAINTENANCE

EQUIPMENT

**IO-COMM**

FAULT

IO & Communication Status

Hardware Input Status

Encoder: Negative Infeed PE: BLOCK Reject Signal: OFF Peg Sensor 1: CLEAR Peg Sensor 2: CLEAR

IO-Link Output Status

Output Port1 Value: 0 Output Port2 Value: 0

Hardwired Output Status

Valve 1: OFF Valve 2: OFF

Communication Input Words (From PLC to ISC)

WORD 00: 0 WORD 01: 0 WORD 02: 0 WORD 03: 0 WORD 04: 0 WORD 05: 0

WORD 06: 0 WORD 07: 0 WORD 08: 0 WORD 09: 0 WORD 10: 0 WORD 11: 0

WORD 12: 0 WORD 13: 0 WORD 14: 0 WORD 15: 0

Communication Output Words (From ISC To PLC)

WORD 00: 18 WORD 01: 65535 WORD 02: 0 WORD 03: 1 WORD 04: 4 WORD 05: 15

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IP Address: 192.168.1.147

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S/N: test4

1. Words received by the ISC CAM from the Line PLC through the ethernet network
2. See ISC CAM Interlocks file for details

## 6. Fault Page

# End in Mind

- Display the status of the faults generated by the ISC CAM in human readable interface.
- Refer to the ISC CAM Interlocks Document for details and ISC Troubleshooting document for actions
- 'Read only'
- Intended users: all users



# Fault 0-7

ISC CAM CONFIGURATION

Fault Overview

**FAULT**

Fault Code 0 : Encoder Fault	OK	✓
Fault Code 1 : Motor Signal is Off	OK	✓
Fault Code 2 : Belt too Slow	OK	✓
Fault Code 3 : Belt Too Fast	OK	✓
Fault Code 4 : JAM Product Sensor 1	OK	✓
Fault Code 5 : JAM Product Sensor 2	OK	✓
Fault Code 6 : JAM Product Sensor 3	OK	✓
Fault Code 7 : Peg Sensor Blocked	OK	✓
Fault Code 8 : Peg not seen while expected	OK	✓
Fault Code 9 : GAP Fault	OK	✓
Fault Code 10 : Power Supply (Low Voltage)	OK	✓
Fault Code 11 : Current Draw High	OK	✓
Fault Code 12 : IO-Link Fault port C0	OK	✓
Fault Code 13 : IO-Link Fault port C1	OK	✓
Fault Code 14 : IO-Link Fault port C2	OK	✓
Fault Code 15 : IO-Link Fault port C3	OK	✓


© Intralox 2021 IP Address: 192.168.1.147 MAC Address: 00:07:46:8b:5d:64 SW Version: V1.12 DPE Model: S7050 ARB S/N: test4


- **Fault Code 0**  
No encoder signal received from encoder
- **Fault Code 1**  
Encoder pulsing but no signal received from Line PLC for motor on.
- **Fault Code 2**  
Belt speed is slower than minimum recommended speed. See Functional Layout for minimum speed.
- **Fault Code 3**  
Belt speed is faster than maximum recommended speed. See Functional Layout for maximum speed
- **Fault Code 4**  
Infeed Product sensor blocked , see ISC troubleshooting guide.
- **Fault Code 5**  
Optional. See Functional Layout for configuration of Intralox Equipment
- **Fault Code 6**  
Optional. See Functional Layout for configuration of Intralox Equipment
- **Fault Code 7**  
Only applicable to AIM technology. Peg sensor blocked 1 or 2 (if applicable), see ISC troubleshooting guide.





# Fault 8-15


ISC CAM CONFIGURATION


 LIVE INFO

 SETTINGS

 MAINTENANCE

 EQUIPMENT

 IO-COMM

 FAULT

Fault Overview

Fault Code 0 : Encoder Fault	OK	✓
Fault Code 1 : Motor Signal is Off	OK	✓
Fault Code 2 : Belt too Slow	OK	✓
Fault Code 3 : Belt Too Fast	OK	✓
Fault Code 4 : JAM Product Sensor 1	OK	✓
Fault Code 5 : JAM Product Sensor 2	OK	✓
Fault Code 6 : JAM Product Sensor 3	OK	✓
Fault Code 7 : Peg Sensor Blocked	OK	✓

Fault Code 8 : Peg not seen while expected

OK

✓

Fault Code 9 : GAP Fault

OK

✓

Fault Code 10 : Power Supply (Low Voltage)

OK

✓

Fault Code 11 : Current Draw High

OK

✓

Fault Code 12 : IO-Link Fault port C0

OK

✓

Fault Code 13 : IO-Link Fault port C1

OK

✓

Fault Code 14 : IO-Link Fault port C2

OK

✓

Fault Code 15 : IO-Link Fault port C3

OK

✓

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IP Address: 192.168.1.147

MAC Address: 00:07:46:8b:5d:64

SW Version: V1.12

DPE Model: S7050 ARB

S/N: test4

- **Fault Code 8**  
Only applicable to AIM Technology  
Peg missing in the belt.
- **Fault Code 9**  
See Functional Layout for min gap value
- **Fault Code 10**  
Power supply low voltage. See ISC troubleshooting guide.
- **Fault Code 11**  
Current draw too high. , see ISC troubleshooting guide.
- **Fault Code 12**  
Only applicable to RnR Technology  
Optional. See Functional Layout for configuration of Intralox equipment
- **Fault Code 13**  
Only applicable to RnR Technology  
See Functional Layout for configuration of Intralox equipment and ISC troubleshooting guide.
- **Fault Code 14**  
Only applicable to RnR Technology  
Optional. See Functional Layout for configuration of Intralox equipment , and ISC troubleshooting guide.
- **Fault Code 15**  
Only applicable to RnR Technology  
Optional. See Functional Layout for configuration of Intralox equipment and ISC troubleshooting guide.