

### Virtual HMI User Instructions

### ISC CAM S70X0 Technology

Version 1.1 29 August 2023

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  - Maintenance
  - Equipment
  - IO-Communication
  - Fauts



# Intended design and use of Virtual HMI

- Virtual HMI facilitates the interaction of non-controls experts with the Intralox equipment to:
  - commission,
  - adjust key operating parameters,
  - communicate faults,
  - communicate basic operating log data.

# How to use this document

- Additional documents from the Intralox User Manual
  - Mechanical drawing of Intralox Equipment
    - Dimensions of Intralox equipment and position of the components
  - Functional layout drawing of Intralox equipment
    - Application information: product trajectories, belt speeds, min product gaps,
  - ISC Interlocks Document
  - ISC Troubleshooting Guide



# Good to know

- Default IP Address: 192.168.1.254
- IP address displayed on the HMI updates only after reboot of the ISC CAM (power off/on).
- All parameters/values displayed on HMI are available on the ethernet network

- Click on "Submit" button to implement changes on the 'fly'.
- Units: SI
- IDL: Intralox Divert Logic



### **Connection to the Virtual HMI**

# How to connect to the Virtual HMI?

- Connect with a laptop to the ethernet network of the ISC CAM
  - If the ISC CAM is not connected to any ethernet, connect directly to the ethernet port of the ISC CAM.
- Write the IP address of the ISC CAM on the navigation bar of an internet browser such as Microsoft Edge, Google Chrome, Mozilla Firefox or similar.
  - If the IP address of the ISC CAM is unknown, please request it to the responsible/manager of PLC network or use the Intralox Service Tool available on <a href="https://www.intralox.com/isccam">www.intralox.com/isccam</a>
  - Default IP address: 192.168.1.254



### **HMI Overview**

# Number of pages & high level Description

- The Virtual HMI has 6 pages
  - 1. Live: landing page
  - 2. Settings
  - 3. Maintenance
  - 4. Equipment
  - 5. IO-Communication
  - 6. Faults

•					intral
ISC CAM CONFIGURATION	Live Info				
	System	Belt	Infeed Sensor	GAP	
LIVE INFO	ок 🕑 I	RUNNING 🕑	вгоск ⊘	O	К 🕑
BETTINGS					
HIL MAINTENANCE	ThroughputBelt Speed5 ppm8 m/min		Time Belt Usage hrs 0km	GAP Faults	-
					1
A FAULT	Divert Information				
	Divert 0	Activations	138	Avg/min:	5
	Divert 1 OFF	ON/OFF Activations:	0	Avg/min:	0
	Divert 2 OFF	ON/OFF Activations:	0	Avg/min:	0
		Destination Net	t Product Current	Gap At Infeed	Minimum Gap At Infeed
		0	1	323 mm	65 mm
© Intralox 2021 IP Address: 192.168.1.14	7 MAC Address: 00:07:46:8b:5d:64	SW Version: V1.	12 DPE Model:	S800 AIM	S/N: test3



# Interface Overview

•					intr
SC CAM CONFIGURATION	Live Info				
	System	Belt	Infeed Sensor	GAF	× ⊘
SETTINGS HAINTENANCE EQUIPMENT IO-COMM	ThroughputBelt Speed5 ppm8 m/min		Time Belt Usage hrs 0km	GAP Fault 0	S
<u>FAULT</u>	Divert Information				
$\mathbf{A}$	Divert 0	Activations	138	Avg/min:	5
	Divert 1 OFF	ON/OFF Activations	0	Avg/min:	0
	Divert 2 OFF	ON / OFF Activations	0	Avg/min:	0
		Destination Ne: 0		: Gap At Infeed 1323mm	Minimum Gap At Infeed 65 mm
Intralox 2021 IP Address: 192.168.1.147	MAC Address: 00:07:46:8b:5d:64	SW Version: V1.	12 DPE Model:	S800 AIM	S/N: test3

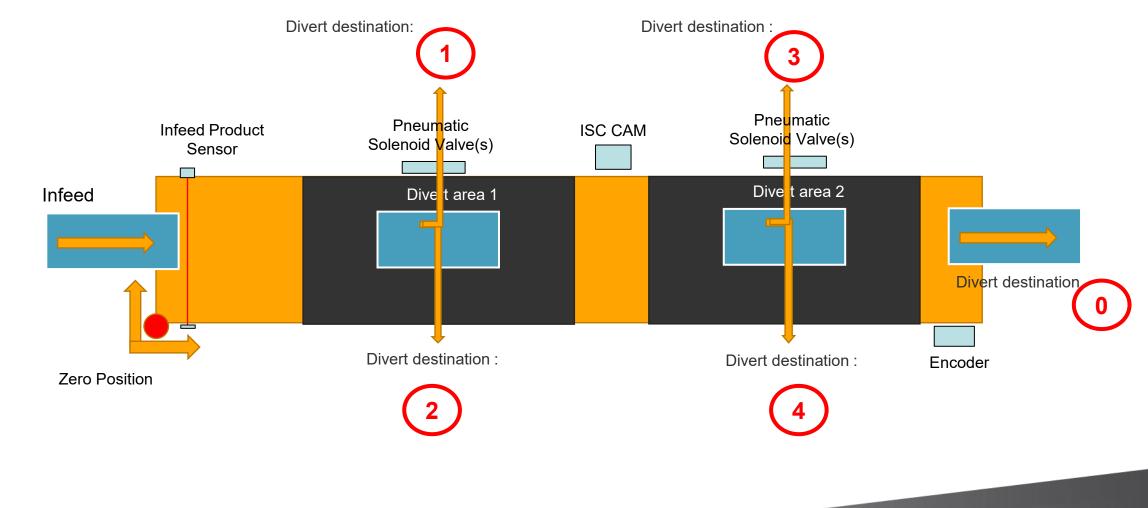
- 1. Navigation pannel
  - Live Info
  - Settings
  - Maintenance
  - Equipment
  - IO-COMM
  - Fault

### 2. Bottom Information Bar

- 1. IP Address of ISC CAM
- 2. MAC Address: electronic unique identifier
- 3. SW Version: Intalox Divert Logic Version
- 4. DPE Model: Intralox Product Family
- 5. S/N: serial number of the Intralox equipment
- 3. Page Unique Information
- 4. Live bit



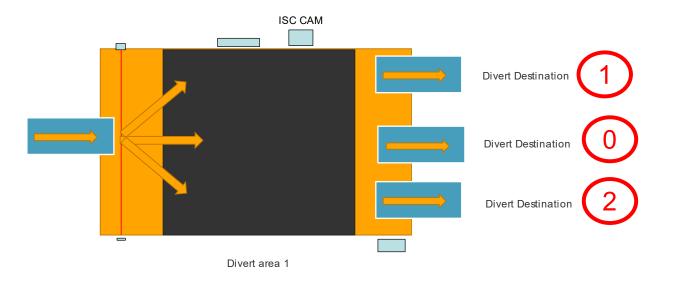
# **Intralox Sorters**





## **Intralox Switch**

### **Intralox Switch**





1. Live page

# End in Mind

- Provide an overview of the status of Intralox equipment using real-time operating data. The data is generated from the field components:
  - Infeed product sensor,
  - encoder,
  - solenoids valves
- 'Read only' page
- Intended users: Any user such as equipment operator, controls engineers, maintenance tech



# Live Info – Indicators

•			intra di seconda di se	alox.
ISC CAM CONFIGURATION	Live Info		6.2	
<ul> <li>LIVE INFO</li> <li>SETTINGS</li> </ul>	System	Belt Infeed Sensor		٠
<u>BELTTINGS</u> <u>BELTTINGS</u> <u>MAINTENANCE</u> <u>EQUIPMENT</u> <u>IO-COMM</u>	Throughput Belt Speed 5ppm 8m/min	Run Time     Up Time     Belt Usage       0 hrs     0 hrs     0 km	GAP Faults 0	•
FAULT	Divert Information	Activations: 138	Avg/min: 5	
	Divert 1 OFF	ON/OFF Activations: 0	Avg/min: 0	
	Divert 2	ON/OFF Activations: 0	Avg/min: 0	
			Gap At Infeed Minimum Gap At Infeed 1323mm 65mm	
© Intralox 2021 IP Address: 192.168.1.147	MAC Address: 00:07:46:8b:5d:64	SW Version: V1.12 DPE Model:	S800 AIM S/N: test3	

System

General status of the system to run

Belt

Status of the belt.

**Infeed Sensor** 

Status infeed Product Sensor.

Gap

Status of gap between 2 consecutive products measured by the infeed product sensor. See page faults for definition of GAP not "OK".

Gap shorter than "Min Gap at Infeed" triggers fault signal to PLC. See troubleshooting guideline.



# **Live Info – Indicators**

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ISC CAM CONFIGURATION	Live Info				lor pr	- Nu
	System	Belt	Infeed Sensor	GAP		in <sup>-</sup> ins
	ок 🕑		вгоск 🕗	OK	$\odot$	Belt
BETTINGS	1.8 2					Lir
(+++) MAINTENANCE	Throughput         Belt Speed           5ppm         8m/min		Time Belt Usage Ohrs Okm	GAP Faults		
				<u> </u>	•	(Belt
					,	Tir It c
FAULT	Divert Information					en
	Divert 0	Activations	s: 138	Avg/min: 5	۰	Uр Т
		ON/OFF Activations				- Tir
		State and a fill a follow		o 2		ро
	Divert 2 OFF 🛆	ON/OFF Activations	s: 0	Avg/min: 0	٠	Belt
		Destination Ne	ext Product Current C	Gap At Infeed	Minimum Gap At Infeed	
		0	1:	323 mm	65 mm	To pu
					٠	Gap
© Intralox 2021 IP Address: 192.168.1.147 MA	C Address: 00:07:46:8b:5d:64	SW Version: V1	.12 DPE Model:	S800 AIM S/	N: test3	- To pu

### bughput

umber of products crossing the infeed product sensor the last minute, updated every minute (not stantaneously)

### Speed

near belt speed.

### t) Run Time

me Duration since ISC CAM is powered on first time. only increases when the belt is moving (receiving coder pulses)

### Time

me duration since the ISC CAM was last time owered on.

### Usage

otal distance travelled by the belt since first encoder lse.

### Fault

otal number of 'Gap Not OK' since the first encoder Ilse. See page faults for definition of GAP not "OK".



# Live Info – Divert Information

					int
CAM CONFIGURATION	Live Info				
	System	Belt	Infeed Sensor	GAP	
LIVE INFO	ок 🕑		BLOCK (	V Oł	$\checkmark$
SETTINGS					
MAINTENANCE	ThroughputBelt Spec5 ppm8 m/mir		D Time Belt Usa		
EQUIPMENT					
IO-COMM					
FAULT	Divert Information				
	Divert 0	Activation	s: 138	Avg/min:	5
	Divert 1 OFF	ON / OFF Activation	s: 0	Avg/min:	0
	Divert 2 OFF	ON/OFF Activations	s: 0	Avg/min:	0
	Divert 2 OFF	ON/OFF Activation		Avg/min: ent Gap At Infeed	0 Minimum Gap At Infeed

Divert Number

Zone counting starts from infeed of the Intralox equipment

### **ON/OFF** button

ON: zone is available to divert products

OFF: zone is not available to divert products

The ISC CAM would not activate this exit even if the LINE PLC indicates it.

Use the "OFF" button when a zone needs to be temporarily unavailable. Ex: maintenance task.

### Activations

Total number of activations of the divert since first encoder pulse received by the ISC CAM (absolute number)

Avg per Minute: products crossing the infeed product sensor in the last minute, update every 60 seconds

### Destination Next Product

Destination assigned to next product crossing the Infeed Product Sensor.

### Current Gap at Infeed

Gap measured by Infeed Product sensor between 2 products. Max gap displayed is the length of the Intralox conveyor.

### Minimal Gap at Infeed

Minimal required gap between 2 products for the Intralox equipment to operate correctly. Functional Layout and ISC Troubleshoeting guideline.



## **2. Settings Page**

# Setting: End in Mind

- Provides the ability to modify key operating parameters (settings) of the Intralox equipment to optimise the trajectory of products.
- 'Read and Write'. Option to import and export 'Application setting files'
- Intended users
  - Technical operators looking for adjusting the performance of the Intralox equipment. Ex. maintenance tech



# **Setting General**

•							intralox
ISC CAM CONFIGURATION	Settings	Select File:	Choose Files No file chosen Ir	nport Data	Filename:		Export Settings
			General Setti		Status: mac	nine constants file I	oaded
	Internal Count 0:	0	Internal Count 1:	0	Internal Cou	nt 2:	0
(a) <u>SETTINGS</u>			General Setti	ings			
HIT MAINTENANCE	PE Position Offset:	0 mm			Default Destir	ation:	0
B EQUIPMENT	Min Product Length:	0 mm			Retain D	ivert OFF	~
E <u>IO-COMM</u>		Area 1			Are	a 2	
FAULT	Divert Offset:	0 mm			Divert Of	fset:	0 mm
	Activation Delay Overrid	e: 0 ms			Activation Delay	Override:	0 ms
	Deactivation Delay Overrid	e: 0 ms			Deactivation Delay	Override:	0 ms
		Submit" mplement nges					
IP Address: 192.168.1.147	MAC Address: 00:07:46:8b:5c	:64	SW Version: V1.12	DPE Model:	S800 AIM	S/N:	test3

### Import Setting Button

Import to the ISC CAM backup application setting files to (extension ".apl"). Ex: factory setting

### Export Data Button

Export application setting files to generate backup

### Internal Count 0, 1 and 2

Slugs/Train functionality. Number of products allocated to divert #. Only applicable when ISC CAM is working in "Internal Model", see HMI Page "Equipment".

### Min Product Length

Minimum distance the infeed PE signal must be stable, to be accepted as product read. Shorter distances will be considered 'noise' or "product debris" such as tape of shrink plastic.

### PE Position OffSet

Infeed Product Sensor distance from the Zero Position. See Mechanical Drawing.

### Default Destination

Destination of product when no signal is received from the Line PLC (external mode) or no slugs/train function is set (internal mode)

### Retain Divert

Divert activation changes when product needs change direction



# **Setting General**

•				intralog
ISC CAM CONFIGURATION	Settings	Select File: Choose Files No f	file chosen Import Data   Filename:	Export Settings
		Ba	alance Settings	
	Count 0:	Count 1: 0 Count	nt 2: 0 Count 3: 0	Count 4: 0
BETTINGS		General Settings	Ir	nfeed 2 Settings
	PE Position Offset:	0 mm Default Destination:	Divert Offset to Left	:0 mm
B EQUIPMENT	Min Product Length:	0 mm Retain Divert:	Divert Offset to Right:	: 0 mm
B IO-COMM		Area 1	Ar	rea 2
FAULT	Divert Offset to Left:	0 mm	Divert Offset to Le	oft: 0 mm
	Divert Offset to Right:	0 mm	Divert Offset to Righ	ht: 0 mm
	Divert Mode: Tr	ailing Edge 🗸	Divert	Mode: Trailing Edge 🗸
	Divert Distance Overric	le: 0 mm	Divert Distance Overri	ide: 0 mm
	Activation Delay Ove	erride: 0 ms	Activation Dela	ay Override: 0 ms
Click "Submit" button to implement	Submit			
changes				
© Intralox 2021 IP Address: 192.168.1.147	MAC Address: 00:07:46:8	b:5d:64 SW Version: V1.	.12 DPE Model: S7050 ARB	S/N: test4

### **Divert OffSet**

Divert area distance from the position defined by Intralox. See Mechanical Drawing.

### **Divert Mode**

Predefine setting for triggering start of movement for diverting/sorting the products. See image in next page for explanation

### **Divert Distance Override**

Applicable to divert area, not divert zone

**Divert distance:** Lateral travel distance of the product (perpendicular to belt travel direction) measured with the encoder pluses. See image in next page for explanation.

Default: length of the activation area

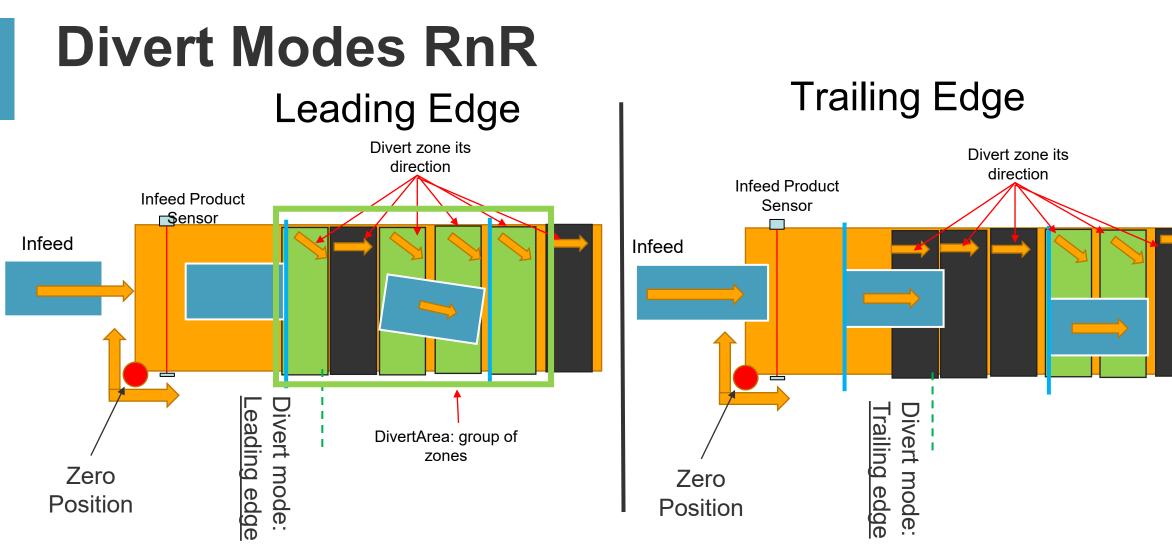
### **Activation Delay Override**

This value considers mechanical delays of the activation system of the Intralox equipment.

### **SUBMIT BUTTON**

Click button for making the modifications on the IDL effective.





<u>Leading Edge [Standard]</u>: activation is triggered when leading edge of the product reaches the end of divert area/zone. Use this setting for maximizing the total divert angle of the product trajectory. <u>Trailing Edge:</u> activation is triggered when trailing edge of the product reaches the start of divert area/zone. Use this setting for minimizing the skewing of the product while moving on the Intralox equipment



### **3. Maintenance Page**

# End in Mind

- Display the 'equipment log' with <u>absolute</u> counter values
- 'Read only', ability to export counter files.
- Intended users: maintenance.

## Maintenance

ISC CAM CONFIGURATION	Maintenance			Filename:	Sav	ve Counters
				Status:	machine constants file loaded	
			Counters			
LIVE INFO	Up Time:	0 hrs	Belt Runtime:	0 hrs	Belt Usage:	0 km
(a) <u>SETTINGS</u>	Product Count:	157	GAP Fault Count:	0	Divert 0 Count:	169
HIL MAINTENANCE	Divert 1 Count:	0	Divert 2 Count:	0		
B EQUIPMENT						
FAULT						
A FAULT						
FAULT						
AULT FAULT						
AULT FAULT						
EAULT						

#### Up time

Time elapsed since the ISC CAM was powered on. It resets to zero when the ISC CAM is powered off.

#### **Belt Run Time**

Time elapsed since the ISC CAM received the first encoder pulse. It only increments when the ISC CAM receives encoder pluses. It never resets to zero

#### Belt Usage

Total distance travelled by the belt since first encoder pulse. It never resets to zero

#### **Product Count**

Total count number of products that passed the infeed product sensor (absolute value) since first encoder pulse.

### **GAP Fault Count**

Total number of 'Gap Not OK' since the first encoder pulse. See page faults for definition of GAP not "OK".

### Divert 0, 1, 2

Total number of activations of each divert since first encoder pulse .

### **Save Counters BUTTON**

Click button to export the counter values. File extension is 'cnt' and requires Intralox tool to make it readable.



## **4. Equipment Page**

# End in Mind

- Ability to modify key operating parameters (settings) of the Intralox equipment to optimise the trajectory of products.
- 'Read and write'
  - Read: read the Intralox equipment mechanical dimensions relevant for the automation of the carryway
  - Write: upload files with the mechanical dimensions of the Intralox equipment
- Intended users
  - Controls engineers integrating the ISC CAM into the Line network (communication)
  - Maitenance operators troubleshooting
- See Functional Layout and Mechanical Drawing



# **Equipment - Application Data**

•				intralox
ISC CAM CONFIGURATION	Equipment		Select File: Choose	Files No file chosen Import Data
		Applica	Status: n	nachine constants file loaded
LIVE INFO	Application: Switch	Activation Type: R&R 1-3	Belt Type: S7050 ARB	Minimum GAP: 65 mm
( SETTINGS	Hardwired Signal: Disable 🗸	Run Mode: Internal 🗸	Sensor Mode: Light On 🗸	Fault Override: 0
		Belt	Data	
EQUIPMENT	Conveyor Length: 1465 mm	Belt Width: 2007 mm	Sprocket Teeth: 10	Pitch: 81 mm
<u>IO-COMM</u>	Encoder Resolution: 64	Belt Traveled/Pulse: 3.96 mm/P	Maximum Speed: 90 m/min	Minimum Speed: 0 m/min
A FAULT		Dive	rt Data	
	Divert Area Count: 1	Zone Length: 64 mm	Inf. Sensor Count: 1	PE Position: 135
	Valve Placement: Left			
	Are	ea 1	Ar	ea 2
Click "Submit"	Position: 126 mm	Activation Delay: 55 ms	Position: 1547 mm	Activation Delay: 22 ms
button to implement changes		Zone Count: 7	Zon	e Count: 2
	Submit			
© Intralox 2021 IP Address: 192.168.1.147	MAC Address: 00:07:46:8b:5d:64	SW Version: V1.12	DPE Model: S7050 ARB	S/N: test4

### Application

Type of functionality that the Intralox equipment is performing when diverting products: Sorter or Switch

Activation Type

Type of mechanical activation mechanism used for engaging with Intralox belt for diverting products: PopUp, RnR or AIM

• Belt Type

Intralox Belt series used in the Intralox equipment.

### Minimum Gap

Minimum distance between products at the infeed of Intralox See Functional Layout

### Hardware Signal

Selections: enable or disable.

Hardwire signal "enable" results that ONLY the 1st divert reacts to the discrete signal of 24VDC to activate. The discrete signal has priority over the ethernet signal. Use hardware signal when the Intralox equipment has a high-speed reject

### Run Mode

•

Selections: Internal or external

Internal Mode: ISC CAM operates in autonomous mode with an internal counter for diverting products

External Mode: ISC CAM requires the input signal from the Line PLC for diverting (or not) each product.

### Sensor Mode

Selection: Light On / Dark On

Applicable to infeed product sensor. Use only for replacement

### Fault Override

Mask - Selection: number, overrides faults. See HMI Page "Faults".



# **Equipment – Belt Data**

				intr
SC CAM CONFIGURATION	Equipment		Select File: Choose	Files No file chosen Import Dat
		Applica	Status:	machine constants file loaded
	Application: Switch	Activation Type: R&R 1-3	Belt Type: S7050 ARB	Minimum GAP: 65 mm
B SETTINGS	Hardwired Signal: Disable V	Run Mode: Internal 🗸	Sensor Mode: Light On 🗸	Fault Override:
HAINTENANCE		Belt	Data	
B EQUIPMENT	Conveyor Length: 1465mm	Belt Width: 2007 mm	Sprocket Teeth: 10	Pitch: 81 mm
<u>IO-COMM</u>	Encoder Resolution: 64	Belt Traveled/Pulse: 3.96 mm/P	Maximum Speed: 90 m/min	Minimum Speed: 0 m/min
A FAULT		Dive	rt Data	
	Divert Area Count: 1	Zone Length: 64 mm	Inf. Sensor Count: 1	PE Position: 135
	Valve Placement: Left			
	Area	a 1	A	rea 2
	Position: 126 mm	Activation Delay: 55 ms	Position: 1547 mm	Activation Delay: 22 ms
Click "Submit" button to implement		Zone Count: 7	Zor	ne Count: 2
changes	Submit			

Conveyor Length

Length in [mm] of the frame of the Intralox equipment.

• Width

•

•

Belt width

- Sprocket Teeth
   Number of teeth of the sprocket
  - Pitch Length of the module of the belt.
  - Encoder Resolution Number of pulses generated by the encoder per revolution. Standard = 64 pulse/rev
- Belt Travel/pulse

Conversion of the belt travel distance in [1/10mm] for each encoder pulse. Dependant of the belt pitch

Maximum Speed

Recommended Maximum belt speed of the Intralox equipment. Functional Layout.

Minimum Speed

Recommended minimum belt speed of Intralox equipment. Functional Layout



# **Equipment Divert Data**

•				intralox
ISC CAM CONFIGURATION	Equipment		Select File: Choose	Files No file chosen Import Data
		A !!		nachine constants file loaded
		Applica	tion Data	
LIVE INFO	Application: Switch	Activation Type: R&R 1-3	Belt Type: S7050 ARB	Minimum GAP: 65 mm
(a) <u>SETTINGS</u>	Hardwired Signal: Disable 🗸	Run Mode: Internal 🗸	Sensor Mode: Light On 🗸	Fault Override: 0
(+++) MAINTENANCE		Belt	Data	
EQUIPMENT	Conveyor Length: 1465 mm	Belt Width: 2007 mm	Sprocket Teeth: 10	Pitch: 81 mm
<u>IO-COMM</u>	Encoder Resolution: 64	Belt Traveled/Pulse: 3.96 mm/P	Maximum Speed: 90 m/min	Minimum Speed: 0 m/min
A FAULT		Diver	t Data	
	Divert Area Count: 1	Zone Length: 64 mm	Inf. Sensor Count: 1	PE Position: 135
	Valve Placement: Left			)
Click "Submit"	Are	a 1	Ar	ea 2
button to implement	Position: 126 mm	Activation Delay: 55 ms	Position: 1547 mm	Activation Delay: 22 ms
changes		Zone Count: 7	Zon	e Count: 2
	Submit			
© Intralov 2021 IP Address: 192 168 1 147 MA	C Address: 00:07:46:8b:5d:64	SW Version: V1 12	DPE Model: S7050 ARB	S/N: tost4

• Divert Area Count

Area # starts from infeed of the Intralox equipment. See image in next page.

- Zone Length Length of the divert zone
- Inf Sensor Count
   Number of Infeed product sensor.
- PE Position

Infeed Product Sensor distance from the Zero Position.

Valve Placement

Mounting side of the Intralox equipment where the valve terminal is mounted



# **Equipment Divert Data**

•				intrali
SC CAM CONFIGURATION	Equipment		Select File: Choose	e Files No file chosen Import Data
		Applica	Status:	machine constants file loaded
	Application: Switch	Activation Type: R&R 1-3	Belt Type: S7050 ARB	Minimum GAP: 65 mm
BETTINGS	Hardwired Signal: Disable 🗸	Run Mode: Internal 🗸	Sensor Mode: Light On 🗸	Fault Override: 0
) MAINTENANCE		Bel	t Data	
3 EQUIPMENT	Conveyor Length: 1465 mm	Belt Width: 2007 mm	Sprocket Teeth: 10	Pitch: 81 mm
B) <u>IO-COMM</u>	Encoder Resolution: 64	Belt Traveled/Pulse: 3.96 mm/P	Maximum Speed: 90 m/min	Minimum Speed: 0 m/min
FAULT		Dive	rt Data	
	Divert Area Count: 1	Zone Length: 64 mm	Inf. Sensor Count: 1	PE Position: 135
	Valve Placement: Left			
Click "Submit"	Are	ea 1	1	Area 2
button to implement	Position: 126 mm	Activation Delay: 55 ms	Position: 1547 mm	Activation Delay: 22 ms
changes		Zone Count: 7	Zc	one Count: 2
	Submit			

### Position

(Start of) divert area distance from the Zero Position

### Activation Delay

Standard mechanical activation delay between a signal is received by the ISC CAM and the product starts moving on the belt.

Zone Count

Number of zones of each divert area.

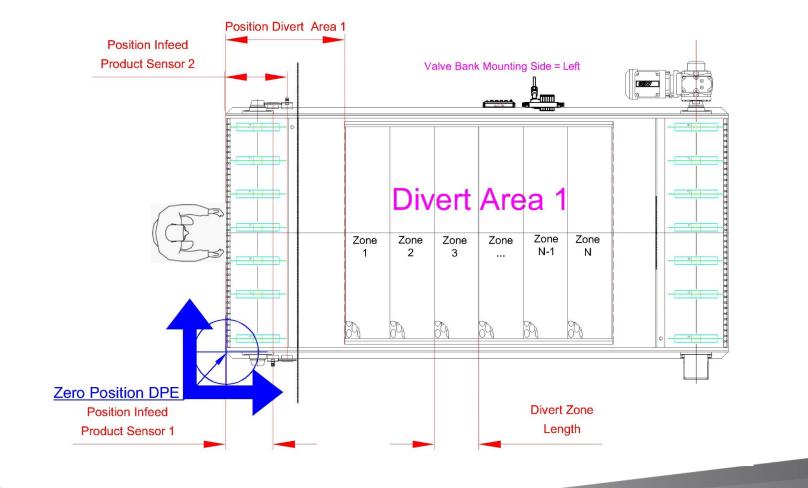
### SUBMIT BUTTON

Push button for making the modifications in the IDL effective.

### NOTE: Area 2 is optional

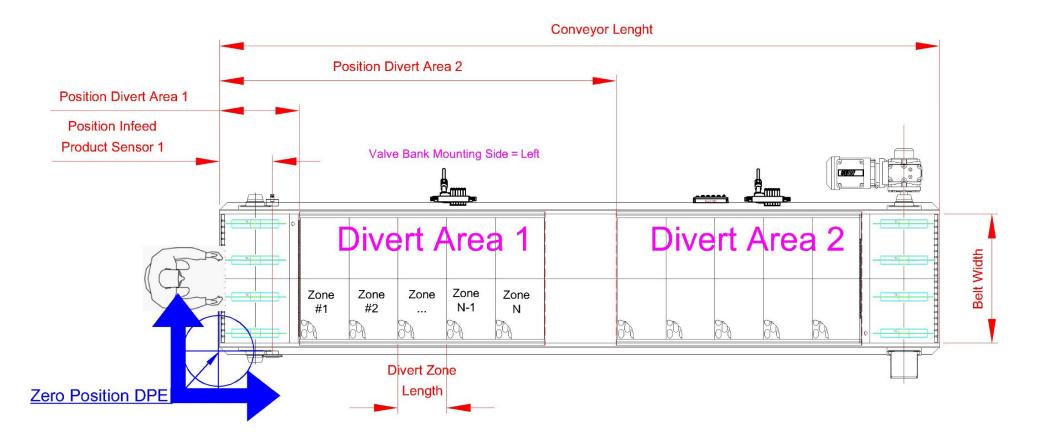


# Appendix 2 : Rack 'n Roll Switch Application





## **Appendix 3: Rack 'n Roll Sorter Application**





5.IO-COMM Page

# **End in Mind**

- Detail the communication status between the ISC CAM with the field components and the line PLC. Please refer to the ISC CAM Interlocks Document for additional information and ISC Troubleshooting document actions
- 'read only'
- Intended users
  - Line control engineers



# **IO-COMM Status**

C CAM CONFIGURATION	10 & Co	mmuni	cation Sta	atus								
	10 4 00	mman										
					Н	ardware	Input Status					
LIVE INFO	Encoder:	Encoder: Negative Infeed PE: BLOCK Reject Signal: OFF Peg Sensor 1: CLEAR Pe								Peg Sensor 2:	CLEA	
) <u>SETTINGS</u>		IO-Link Output Status							Hardwi	ired Ou	tput Status	
) MAINTENANCE	Output Port1 Value:		0	Output	Port2 Value: 0			Val	Valve 1: OFF		Valve 2: OFF	
) <u>EQUIPMENT</u>	Communication Input Words (From PLC to ISC)											
<u>IO-COMM</u>	WORD 00:	0	WORD 01:	0	WORD 02:	0	WORD 03:	0	WORD 04:	0	WORD 05:	0
FAULT	WORD 06:	0	WORD 07:	0	WORD 08:	0	WORD 09:	0	WORD 10:	0	WORD 11:	0
	WORD 12:	0	WORD 13:	0	WORD 14:	0	WORD 15:	0				
		Communication Output Words (From ISC To PLC)										
	WORD 00:	18	WORD 01:	65535	WORD 02:	0	WORD 03:	1	WORD 04:	4	WORD 05:	<mark>1</mark> 5
	WORD 06:	233	WORD 07:	0	WORD 08:	0	WORD 09:	0	WORD 10:	20	WORD 11:	0
	WORD 12:	0	WORD 13:	0	WORD 14:	0	WORD 15:	0				

Encoder

Status of encoder, blinking with each pulse

Infeed PE

Status of infeed product sensor

Reject Signal

Status of hardwire reject signal

Peg Sensor 1

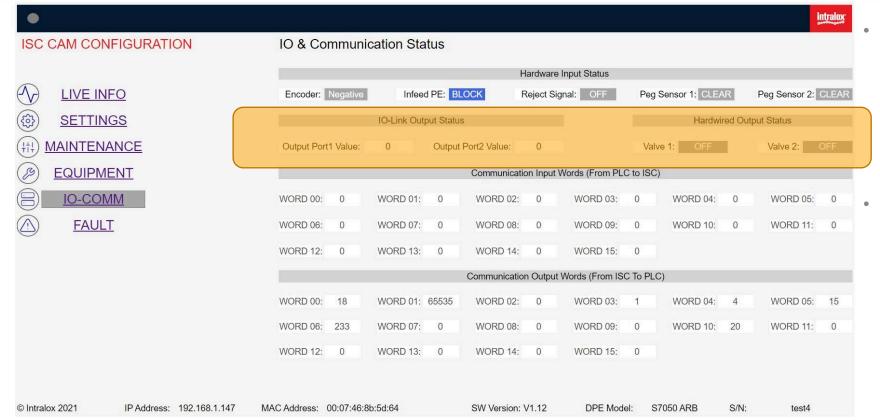
Only applicable for AIM applications. Status of peg sensor of divert 1, blinking with each peg passing the beam the peg sensor (belt has to move)

Peg Sensor 2

Only applicable for AIM applications. Status of peg sensor of divert 2, blinking with each peg passing the beam the peg sensor (belt has to move)



# **IO-COMM Status**



### **IO-Link Output Status**

### Out Port 1 valve

Only applicable to RnR technology. Status of valve bank.

### **Out Port 2 valve (optional)**

Only applicable to RnR technology. Status of valve bank.

### Hardware Output Status

### Valve 1

Only applicable to Popup and AIM technology

OFF: valve is off

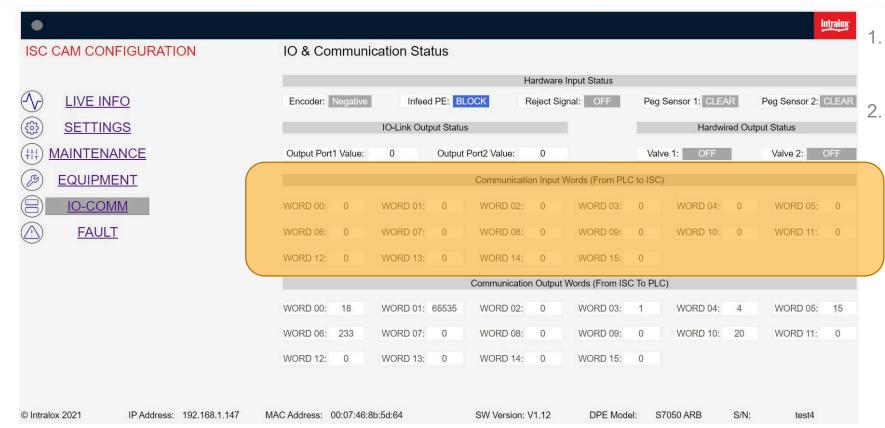
ON: valve is on.

### Valve 2 (optional)

Only applicable to Popup and AIM technology OFF: valve is off ON: valve is on.



# **IO-COMM Input Words**



- Words sent by the ISC CAM to the Line PLC through the ethernet network
- See ISC CAM Interlocks file for details



# **IO-COMM Output Words**

SC CAM CONFIGURATION	IO & Communication Status											
	Hardware Input Status											
	Encoder: Negative	Infeed PE: BL				Peg Sensor 1: CLEAR		Peg Sensor 2: CLE				
<u>SETTINGS</u>		IO-Link Output Status				Hardwired Output Status						
tt) MAINTENANCE	Output Port1 Value:	0 Output Port2 Value:		0		Valve 1: OFF		Valve 2: OFF				
B EQUIPMENT	Communication Input Words (From PLC to ISC)											
<u>IO-COMM</u>	WORD 00: 0	WORD 01: 0	WORD 02:	0 WORD	03: 0	WORD 04:	0	WORD 05:	0			
FAULT	WORD 06: 0	WORD 07: 0	WORD 08:	0 WORD	09: 0	WORD 10:	0	WORD 11:	0			
	WORD 12: 0	WORD 13: 0	WORD 14:	0 WORD	15: 0							
	Communication Output Words (From ISC To PLC)											
	WORD 00: 18	WORD 01: 65535	WORD 02:	0 WORD	03: 1	WORD 04:	4	WORD 05:	15			
	WORD 06: 233	WORD 07: 0	WORD 08:	0 WORD	09: 0	WORD 10:	20	WORD 11:	0			
	WORD 12: 0	WORD 13: 0	WORD 14:	0 WORD	15: 0							

- 1. Words received by the ISC CAM from the Line PLC through the ethernet network
- 2. See ISC CAM Interlocks file for details



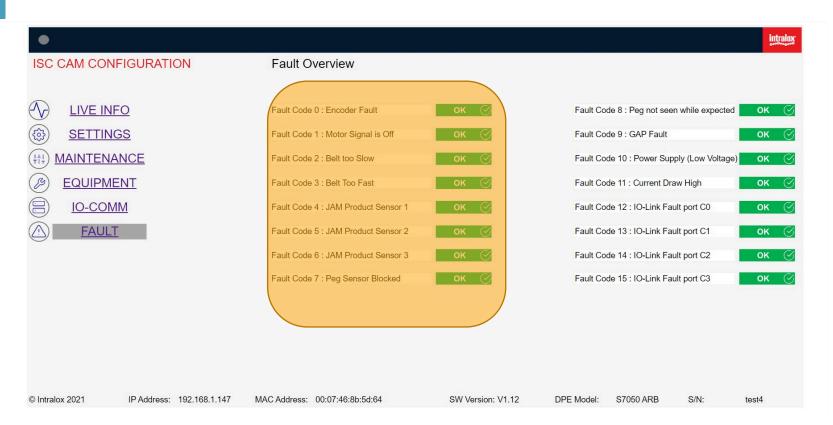


# **End in Mind**

- Display the status of the faults generated by the ISC CAM in human readable interface.
- Refer to the ISC CAM Interlocks Document for details and ISC Troubleshooting document for actions
- 'Read only'
- Intended users: all users



# Fault 0-7



### • Fault Code 0

No encoder signal received from encoder

• Fault Code 1

Encoder pulsing but no signal received from Line PLC for motor on.

• Fault Code 2

Belt speed is slower than minimum recommended speed. See Functional Layout for minimum speed.

• Fault Code 3

Belt speed is faster than maximum recommended speed. See Functional Layout for maximum speed

• Fault Code 4

Infeed Product sensor blocked , see ISC troubleshooting guide.

• Fault Code 5

Optional. See Functional Layout for configuration of Intralox Equipment

• Fault Code 6

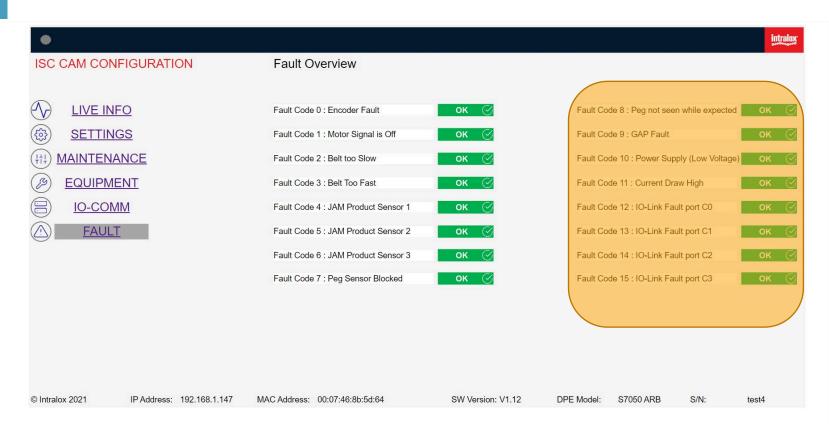
Optional. See Functional Layout for configuration of Intralox Equipment

Fault Code 7

Only applicable to AIM technology. Peg sensor blocked 1 or 2 (if applicable), see ISC troubleshooting guide.



## Fault 8-15



- Fault Code 8
   Only applicable to AIM Technology
   Peg missing in the belt.
- Fault Code 9
   See Functional Layout for min gap value
  - Fault Code 10 Power supply low voltage. See ISC troubleshooting guide.
- Fault Code 11
   Current draw too high

Current draw too high. , see ISC troubleshooting guide.

• Fault Code 12

•

Only applicable to RnR Technology Optional. See Functional Layout for configuration of Intralox equipment

• Fault Code 13

Only applicable to RnR Technology See Functional Layout for configuration of Intralox equipment and ISC troubleshooting guide.

• Fault Code 14

Only applicable to RnR Technology

Optional. See Functional Layout for configuration of Intralox equipment , and ISC troubleshooting guide.

• Fault Code 15

Only applicable to RnR Technology Optional. See Functional Layout for configuration of Intralox equipment and ISC troubleshooting guide.

